## Lecture 13

More dynamic programming!

Longest Common Subsequences, Knapsack, and (if time) independent sets in trees.

#### Announcements

 Exam 3 is live! Please do not ask or discuss examrelated stuff in chat/Q&A during lecture.

• If you find any errors, typos, or omissions during the first 24 hours (EOD today Pacific Time), you can PRIVATELY bring them to the course staff attention (private Ed post would do). We will publicly clarify these in a pinned Ed thread.

We will not answer general clarification questions.
 If something is not clear, state your assumptions.

#### Last time



Not coding in an action movie.



#### Last time



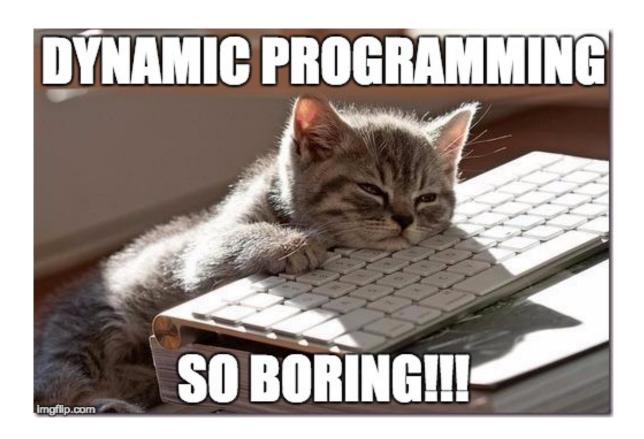
- Dynamic programming is an algorithm design paradigm.
- Basic idea:
  - Identify optimal sub-structure
    - Optimum to the big problem is built out of optima of small sub-problems
  - Take advantage of overlapping sub-problems
    - Only solve each sub-problem once, then use it again and again
  - Keep track of the solutions to sub-problems in a table as you build to the final solution.

#### Today

- Examples of dynamic programming:
  - 1. Longest common subsequence
  - 2. Knapsack problem
    - Two versions!
  - 3. Independent sets in trees
    - If we have time...
    - (If not the slides will be there as a reference)
- Yet more examples of DP in CLRS!
  - Optimal order of matrix multiplications
  - Optimal binary search trees
  - Longest paths in DAGs, ...

#### The goal of this lecture

For you to get really bored of dynamic programming



#### Longest Common Subsequence

How similar are these two species?



DNA:

AGCCCTAAGGGCTACCTAGCTT



DNA:
GACAGCCTACAAGCGTTAGCTTG

#### Longest Common Subsequence

How similar are these two species?





Pretty similar, their DNA has a long common subsequence:

**AGCCTAAGCTTAGCTT** 

DNA:

## Longest Common Subsequence

- Subsequence:
  - BDFH is a subsequence of ABCDEFGH
- If X and Y are sequences, a **common subsequence** is a sequence which is a subsequence of both.
  - BDFH is a common subsequence of ABCDEFGH and of ABDFGHI
- A longest common subsequence...
  - ...is a common subsequence that is longest.
  - The **longest common subsequence** of ABCDEFGH and ABDFGHI is ABDFGH.

#### We sometimes want to find these

Applications in bioinformatics





- The unix command diff
- Merging in version control
  - svn, git, etc...

```
\overline anari — anari@nimbook —...
    cat file1
   cat file2
   ~ diff file1 file2
3d2
5d3
8a7
```

#### Recipe for applying Dynamic Programming

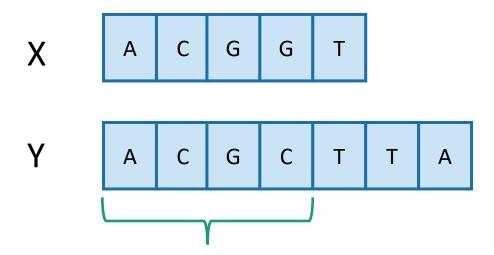
• Step 1: Identify optimal substructure.



- Step 2: Find a recursive formulation for the length of the longest common subsequence.
- Step 3: Use dynamic programming to find the length of the longest common subsequence.
- Step 4: If needed, keep track of some additional info so that the algorithm from Step 3 can find the actual LCS.
- Step 5: If needed, code this up like a reasonable person.

#### Step 1: Optimal substructure

#### Prefixes:



**Notation**: denote this prefix **ACGC** by Y<sub>4</sub>

- Our sub-problems will be finding LCS's of prefixes to X and Y.
- Let C[i,j] = length\_of\_LCS(X<sub>i</sub>, Y<sub>i</sub>)

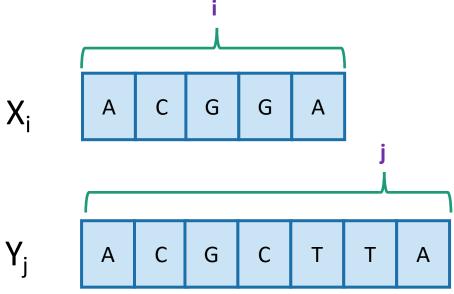
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#### Goal

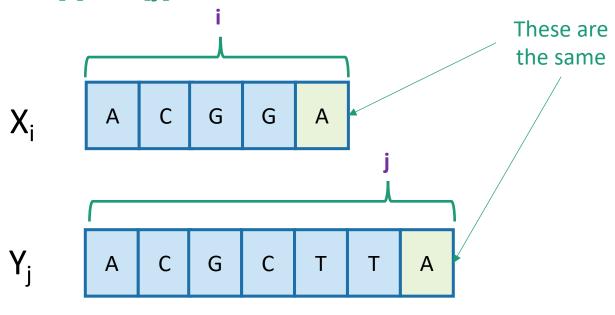
 Write C[i,j] in terms of the solutions to smaller subproblems



#### Two cases

Case 1: X[i] = Y[j]

- Our sub-problems will be finding LCS's of prefixes to X and Y.
- Let C[i,j] = length\_of\_LCS( X<sub>i</sub>, Y<sub>j</sub> )

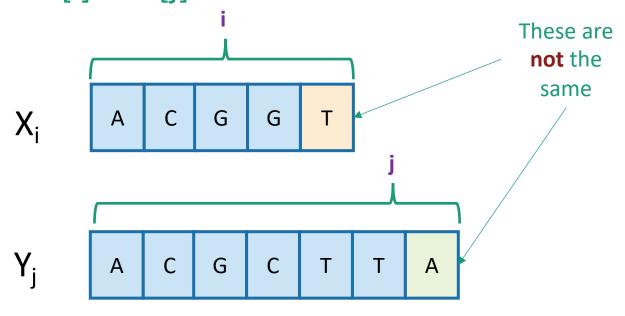


- Then C[i,j] = 1 + C[i-1,j-1].
  - because  $LCS(X_i,Y_j) = LCS(X_{i-1},Y_{j-1})$  followed by A

#### Two cases

Case 2: X[i] != Y[j]

- Our sub-problems will be finding LCS's of prefixes to X and Y.
- Let C[i,j] = length\_of\_LCS(X<sub>i</sub>, Y<sub>i</sub>)



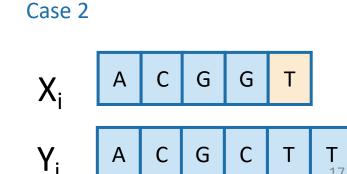
- Then C[i,j] = max{ C[i-1,j], C[i,j-1] }.
  - either LCS(X<sub>i</sub>,Y<sub>j</sub>) = LCS(X<sub>i-1</sub>,Y<sub>j</sub>) and T is not involved,
  - or  $LCS(X_i,Y_i) = LCS(X_i,Y_{i-1})$  and A is not involved,
  - (maybe both are not involved, that's covered by the "or").

# Recursive formulation of the optimal solution

•  $C[i,j] = \begin{cases} 0 & \text{if } i = 0 \text{ or } j = 0 \\ C[i-1,j-1] + 1 & \text{if } X[i] = Y[j] \text{ and } i,j > 0 \\ \max\{C[i,j-1],C[i-1,j]\} & \text{if } X[i] \neq Y[j] \text{ and } i,j > 0 \end{cases}$ 

X<sub>i</sub> A C G G A

Y<sub>j</sub> A C G C T T A



#### Recipe for applying Dynamic Programming

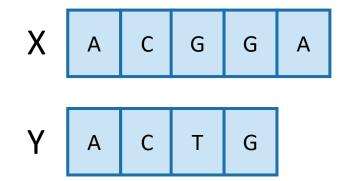
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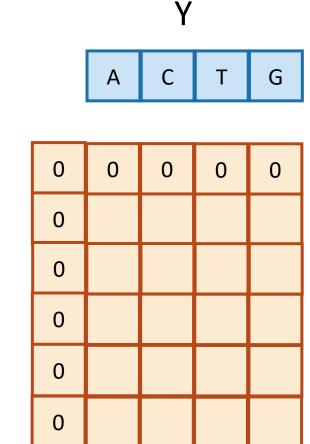
#### LCS DP

- LCS(X, Y):
  - C[i,0] = C[0,j] = 0 for all i = 0,...,m, j=0,...n.
  - **For** i = 1,...,m and j = 1,...,n:
    - **If** X[i] = Y[j]:
      - C[i,j] = C[i-1,j-1] + 1
    - Else:
      - C[i,j] = max{ C[i,j-1], C[i-1,j] }
  - Return C[m,n]

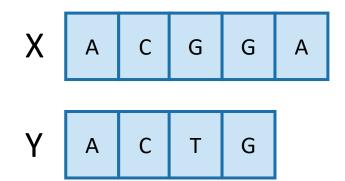
Running time: O(nm)

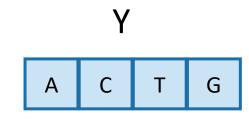
$$C[i,j] = \begin{cases} 0 & \text{if } i = 0 \text{ or } j = 0 \\ C[i-1,j-1] + 1 & \text{if } X[i] = Y[j] \text{ and } i,j > 0 \\ \max\{C[i,j-1],C[i-1,j]\} & \text{if } X[i] \neq Y[j] \text{ and } i,j > 0 \end{cases}$$





$$C[i,j] = \begin{cases} 0 & \text{if } i = 0 \text{ or } j = 0 \\ C[i-1,j-1]+1 & \text{if } X[i] = Y[j] \text{ and } i,j > 0 \\ \max\{C[i,j-1],C[i-1,j]\} & \text{if } X[i] \neq Y[j] \text{ and } i,j > 0 \end{cases}$$





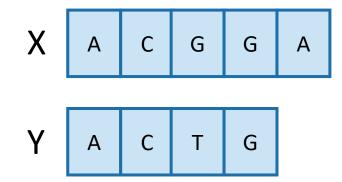
0	0	0	0	0
0	1	1	1	1
0	1	2	2	2
0	1	2	2	3
0	1	2	2	3
0	1	2	2	3

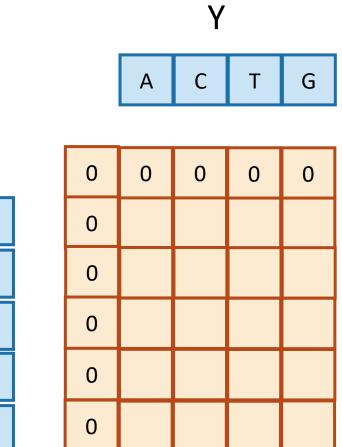
So the LCM of X and Y has length 3.

$$C[i,j] = \begin{cases} 0 & \text{if } i = 0 \text{ or } j = 0 \\ C[i-1,j-1]+1 & \text{if } X[i] = Y[j] \text{ and } i,j > 0 \\ \max\{C[i,j-1],C[i-1,j]\} & \text{if } X[i] \neq Y[j] \text{ and } i,j > 0 \end{cases}$$

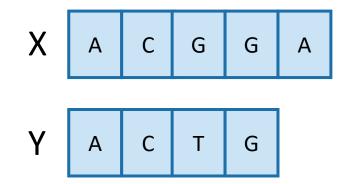
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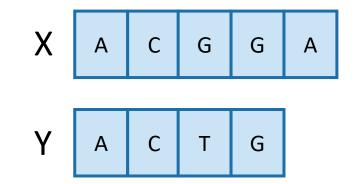
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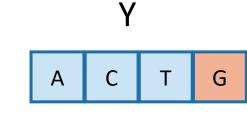


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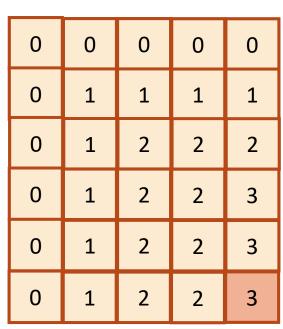
0	0	0	0	0
0	1	1	1	1
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0	1	2	2	3
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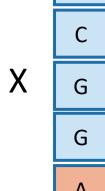


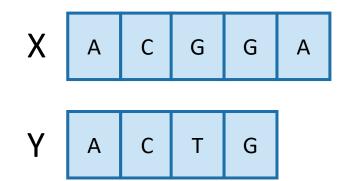


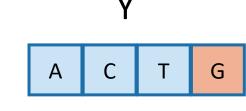
• Once we've filled this in, we can work backwards.



$$C[i,j] = \begin{cases} 0 & \text{if } i = 0 \text{ or } j = 0\\ C[i-1,j-1]+1 & \text{if } X[i] = Y[j] \text{ and } i,j > 0\\ \max\{C[i,j-1],C[i-1,j]\} & \text{if } X[i] \neq Y[j] \text{ and } i,j > 0 \end{cases}$$





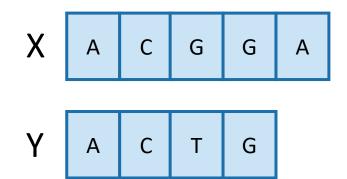


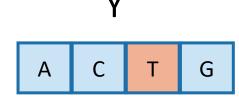
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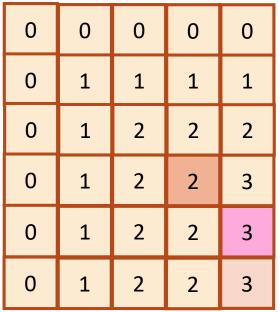
0	0	0	0	0
0	1	1	1	1
0	1	2	2	2
0	1	2	2	3
0	1	2	2	3
0	1	2	2	3

That 3 must have come from the 3 above it.

$$C[i,j] = \begin{cases} 0 & \text{if } i = 0 \text{ or } j = 0 \\ C[i-1,j-1] + 1 & \text{if } X[i] = Y[j] \text{ and } i,j > 0 \\ \max\{C[i,j-1], C[i-1,j]\} & \text{if } X[i] \neq Y[j] \text{ and } i,j > 0 \end{cases}$$



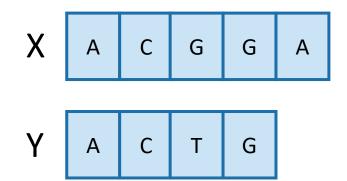


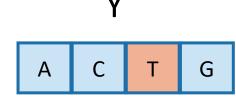


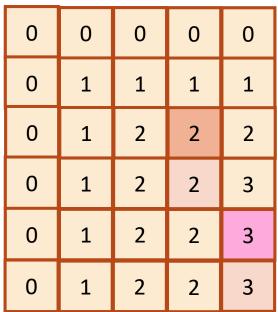
- Once we've filled this in, we can work backwards.
- A diagonal jump means that we found an element of the LCS!

This 3 came from that 2 – we found a match!

$$C[i,j] = \begin{cases} 0 & \text{if } i = 0 \text{ or } j = 0 \\ C[i-1,j-1]+1 & \text{if } X[i] = Y[j] \text{ and } i,j > 0 \\ \max\{C[i,j-1],C[i-1,j]\} & \text{if } X[i] \neq Y[j] \text{ and } i,j > 0 \end{cases}$$



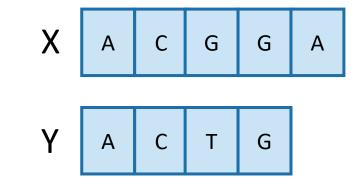


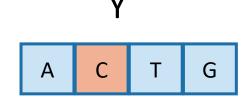


- Once we've filled this in, we can work backwards.
- A diagonal jump means that we found an element of the LCS!

That 2 may as well have come from this other 2.

$$C[i,j] = \begin{cases} 0 & \text{if } i = 0 \text{ or } j = 0 \\ C[i-1,j-1] + 1 & \text{if } X[i] = Y[j] \text{ and } i,j > 0 \\ \max\{C[i,j-1],C[i-1,j]\} & \text{if } X[i] \neq Y[j] \text{ and } i,j > 0 \end{cases}$$

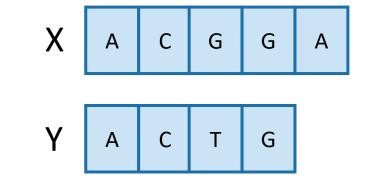


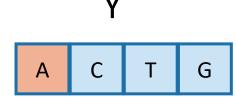


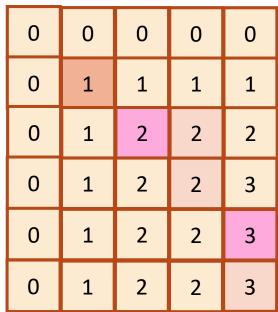
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G

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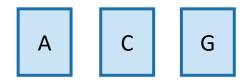
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CG

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- Once we've filled this in, we can work backwards.
- A diagonal jump means that we found an element of the LCS!



#### This is the LCS!

G

Α

$$C[i,j] = \begin{cases} 0 & \text{if } i = 0 \text{ or } j = 0 \\ C[i-1,j-1] + 1 & \text{if } X[i] = Y[j] \text{ and } i,j > 0 \\ \max\{C[i,j-1],C[i-1,j]\} & \text{if } X[i] \neq Y[j] \text{ and } i,j > 0 \end{cases}$$

#### Finding an LCS

- Good exercise to write out pseudocode for what we just saw!
  - Or you can find it in lecture notes.
- Takes time O(mn) to fill the table
- Takes time O(n + m) on top of that to recover the LCS
  - We walk up and left in an n-by-m array
  - We can only do that for n + m steps.
- Altogether, we can find LCS(X,Y) in time O(mn).

#### Recipe for applying Dynamic Programming

- Step 1: Identify optimal substructure.
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- Step 5: If needed, code this up like a reasonable person.

#### Our approach actually isn't so bad

- If we are only interested in the length of the LCS we can do a bit better on space:
  - Since we go across the table one-row-at-a-time, we can only keep two rows if we want.
- If we want to recover the LCS, we need to keep the whole table.
- Can we do better than O(mn) time?
  - A bit better.
    - By a log factor or so.
  - But doing much better (polynomially better) is an open problem!

#### What have we learned?

- We can find LCS(X,Y) in time O(nm)
  - if |Y|=n, |X|=m
- We went through the steps of coming up with a dynamic programming algorithm.
  - We kept a 2-dimensional table, breaking down the problem by decrementing the length of X and Y.

## Example 2: Knapsack Problem

We have n items with weights and values:

Item: 11 Weight: 35 Value: 14 13 20

- And we have a knapsack:
  - it can only carry so much weight:





Capacity: 10











Item: 11 Weight: 35 14 13 Value: 20

#### **Unbounded Knapsack:**

- Suppose I have infinite copies of all items.
- What's the most valuable way to fill the knapsack?









Total weight: 10 Total value: 42

#### • 0/1 Knapsack:

- Suppose I have only one copy of each item.
- What's the most valuable way to fill the knapsack?

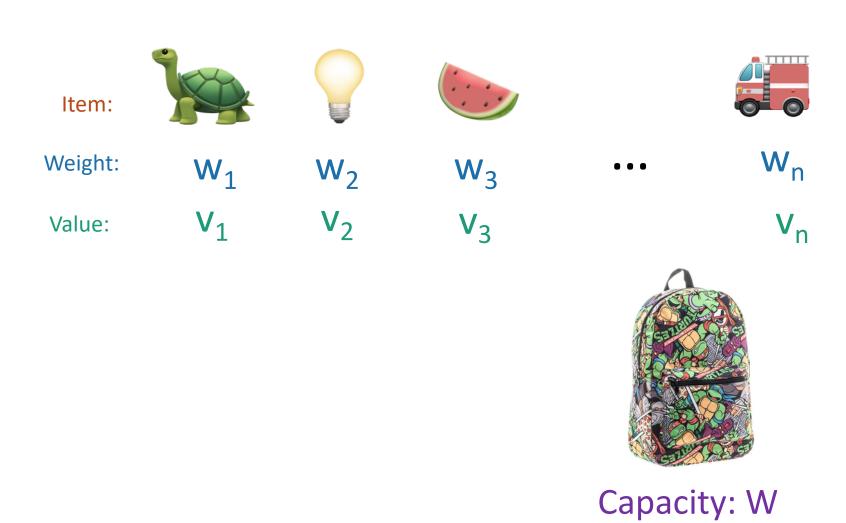






Total weight: 9 Total value: 35

#### Some notation



#### Recipe for applying Dynamic Programming

• Step 1: Identify optimal substructure.



- Step 2: Find a recursive formulation for the value of the optimal solution.
- Step 3: Use dynamic programming to find the value of the optimal solution.
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## Optimal substructure

#### Sub-problems:

• Unbounded Knapsack with a smaller knapsack.

K[x] = value you can fit in a knapsack of capacity x







First solve the problem for small knapsacks

Then larger knapsacks

Then larger knapsacks

# Optimal substructure



Suppose this is an optimal solution for capacity x:

Say that the optimal solution contains at least one copy of item i.





Capacity x Value V

Then this is optimal for capacity x - w<sub>i</sub>:









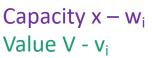


Why?

1 minute think (wait) 1 minute share





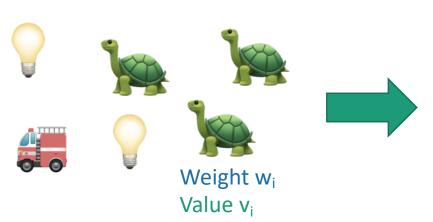


# Optimal substructure



Suppose this is an optimal solution for capacity x:

Say that the optimal solution contains at least one copy of item i.





Capacity x Value V

Then this is optimal for capacity x - w<sub>i</sub>:





If I could do better than the second solution, then adding a turtle to that improvement would improve the first solution.

Capacity x – w<sub>i</sub> Value V - v<sub>i</sub>

### Recipe for applying Dynamic Programming

- Step 1: Identify optimal substructure.
- Step 2: Find a recursive formulation for the value of the optimal solution.
- Step 3: Use dynamic programming to find the value of the optimal solution.
- Step 4: If needed, keep track of some additional info so that the algorithm from Step 3 can find the actual solution.
- Step 5: If needed, code this up like a reasonable person.

### Recursive relationship

Let K[x] be the optimal value for capacity x.

$$K[x] = \max_i \left\{ \begin{array}{c} + \\ \\ \end{array} \right\}$$
 The maximum is over all i so that  $w_i \leq x$ . Optimal way to fill the smaller knapsack

$$K[x] = max_i \{ K[x - w_i] + v_i \}$$

- (And K[x] = 0 if the maximum is empty).
  - That is, if there are no i so that  $w_i \leq x$

### Recipe for applying Dynamic Programming

- Step 1: Identify optimal substructure.
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- Step 3: Use dynamic programming to find the value of the optimal solution.
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### Let's write a bottom-up DP algorithm

- UnboundedKnapsack(W, n, weights, values):
  - K[0] = 0
  - for x = 1, ..., W:
    - K[x] = 0
    - **for** i = 1, ..., n:
      - if  $w_i \leq x$ :
        - $K[x] = \max\{K[x], K[x w_i] + v_i\}$
  - return K[W]

Running time: O(nW)

```
K[x] = \max_{i} \{ \left[ \left( \mathbf{x} - \mathbf{w}_{i} \right) + \mathbf{v}_{i} \right] \}
= \max_{i} \{ K[\mathbf{x} - \mathbf{w}_{i}] + \mathbf{v}_{i} \}
```

#### Can we do better?

- Writing down W takes log(W) bits.
- Writing down all n weights takes at most nlog(W) bits.
- Input size: nlog(W).
  - Maybe we could have an algorithm that runs in time O(nlog(W)) instead of O(nW)?
  - Or even O( n<sup>1000000</sup> log<sup>1000000</sup>(W) )?

- Open problem!
  - (But probably the answer is no...otherwise P = NP)

#### Recipe for applying Dynamic Programming

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- Step 4: If needed, keep track of some additional info so that the algorithm from Step 3 can find the actual solution.
- Step 5: If needed, code this up like a reasonable person.

### Let's write a bottom-up DP algorithm

- UnboundedKnapsack(W, n, weights, values):
  - K[0] = 0
  - for x = 1, ..., W:
    - K[x] = 0
    - **for** i = 1, ..., n:
      - if  $w_i \leq x$ :
        - $K[x] = \max\{K[x], K[x w_i] + v_i\}$
  - return K[W]

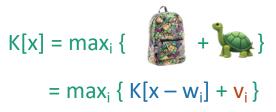
```
K[x] = \max_{i} \{ w_{i} + w_{i} \}
= \max_{i} \{ K[x - w_{i}] + v_{i} \}
```

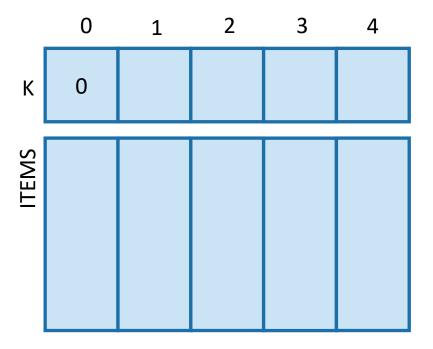
## Let's write a bottom-up DP algorithm

UnboundedKnapsack(W, n, weights, values):

```
    K[0] = 0
    ITEMS[0] = Ø
    for x = 1, ..., W:
```

- K[x] = 0
- **for** i = 1, ..., n:
  - if  $w_i \leq x$ :
    - $K[x] = \max\{K[x], K[x w_i] + v_i\}$
    - If K[x] was updated:
      - ITEMS[x] = ITEMS[x w<sub>i</sub>] U { item i }
- return ITEMS[W]





- UnboundedKnapsack(W, n, weights, values):
  - K[0] = 0
  - ITEMS $[0] = \emptyset$
  - for x = 1, ..., W:
    - K[x] = 0
    - **for** i = 1, ..., n:
      - if  $w_i \leq x$ :

Value:

- $K[x] = \max\{K[x], K[x w_i] + v_i\}$
- If K[x] was updated:
  - ITEMS[x] = ITEMS[x w<sub>i</sub>] U { item i }
- return ITEMS[W]

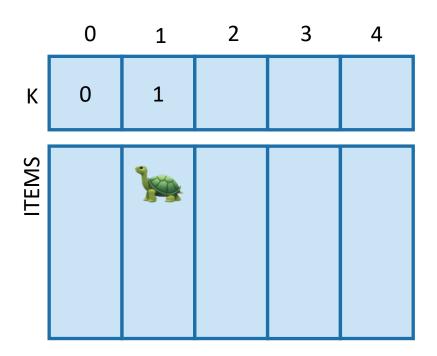




6

4

Capacity: 4



- UnboundedKnapsack(W, n, weights, values):
  - K[0] = 0
  - ITEMS[0] = Ø
  - for x = 1, ..., W:
    - K[x] = 0
    - **for** i = 1, ..., n:
      - if  $w_i \leq x$ :

Value:

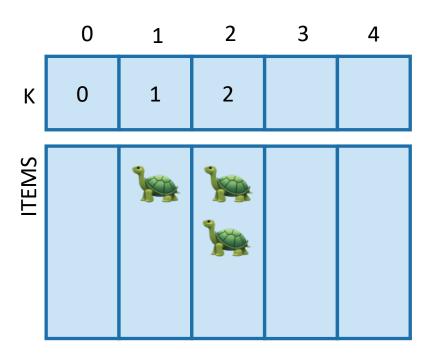
- $K[x] = \max\{K[x], K[x w_i] + v_i\}$
- If K[x] was updated:
  - ITEMS[x] = ITEMS[x − w<sub>i</sub>] U { item i }
- return ITEMS[W]





4

Capacity: 4

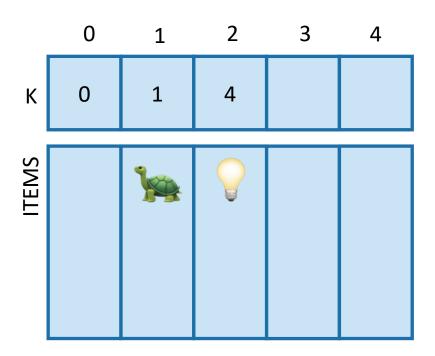


- UnboundedKnapsack(W, n, weights, values):
  - K[0] = 0
  - ITEMS $[0] = \emptyset$
  - for x = 1, ..., W:
    - K[x] = 0
    - **for** i = 1, ..., n:
      - if  $w_i \leq x$ :
        - $K[x] = \max\{K[x], K[x w_i] + v_i\}$
        - If K[x] was updated:
          - ITEMS[x] = ITEMS[x − w<sub>i</sub>] U { item i }
  - return ITEMS[W]



Value: 1 4 6



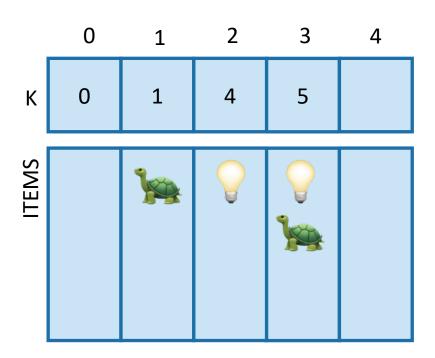


$$ITEMS[2] = ITEMS[0] +$$

- UnboundedKnapsack(W, n, weights, values):
  - K[0] = 0
  - ITEMS $[0] = \emptyset$
  - for x = 1, ..., W:
    - K[x] = 0
    - **for** i = 1, ..., n:
      - if  $w_i \leq x$ :
        - $K[x] = \max\{K[x], K[x w_i] + v_i\}$
        - If K[x] was updated:
          - ITEMS[x] = ITEMS[x w<sub>i</sub>] U { item i }
  - return ITEMS[W]







- UnboundedKnapsack(W, n, weights, values):
  - K[0] = 0
  - ITEMS[0] = Ø
  - for x = 1, ..., W:
    - K[x] = 0
    - **for** i = 1, ..., n:
      - if  $w_i \leq x$ :

Value:

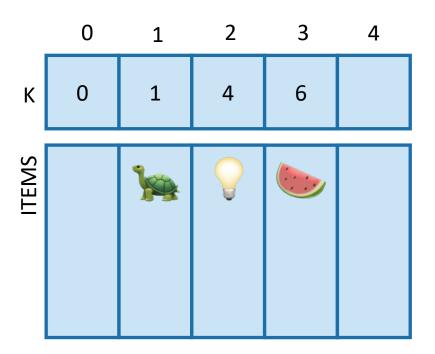
- $K[x] = \max\{K[x], K[x w_i] + v_i\}$
- If K[x] was updated:
  - ITEMS[x] = ITEMS[x − w<sub>i</sub>] U { item i }

4

return ITEMS[W]





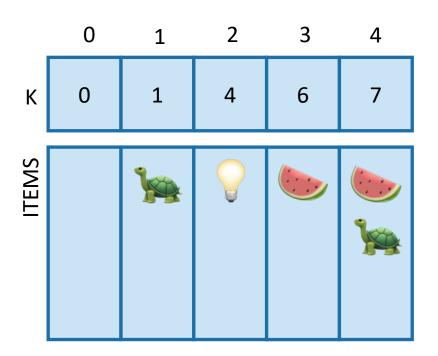


- UnboundedKnapsack(W, n, weights, values):
  - K[0] = 0
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  - for x = 1, ..., W:
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    - **for** i = 1, ..., n:
      - if  $w_i \leq x$ :
        - $K[x] = \max\{K[x], K[x w_i] + v_i\}$
        - If K[x] was updated:
          - ITEMS[x] = ITEMS[x − w<sub>i</sub>] U { item i }
  - return ITEMS[W]





Capacity: 4

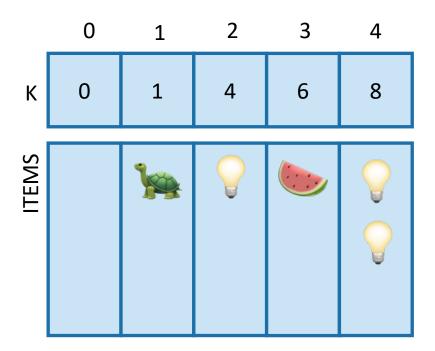


- UnboundedKnapsack(W, n, weights, values):
  - K[0] = 0
  - ITEMS $[0] = \emptyset$
  - for x = 1, ..., W:
    - K[x] = 0
    - **for** i = 1, ..., n:
      - if  $w_i \leq x$ :
        - $K[x] = \max\{K[x], K[x w_i] + v_i\}$
        - If K[x] was updated:
          - ITEMS[x] = ITEMS[x − w<sub>i</sub>] U { item i }
  - return ITEMS[W]





Capacity: 4



$$ITEMS[4] = ITEMS[2] +$$

- UnboundedKnapsack(W, n, weights, values):
  - K[0] = 0
  - ITEMS $[0] = \emptyset$
  - for x = 1, ..., W:
    - K[x] = 0
    - **for** i = 1, ..., n:
      - if  $w_i \leq x$ :
        - $K[x] = \max\{K[x], K[x w_i] + v_i\}$
        - If K[x] was updated:
          - ITEMS[x] = ITEMS[x w<sub>i</sub>] U { item i }
  - return ITEMS[W]





Capacity: 4

### Recipe for applying Dynamic Programming

- Step 1: Identify optimal substructure.
- Step 2: Find a recursive formulation for the value of the optimal solution.
- Step 3: Use dynamic programming to find the value of the optimal solution.
- Step 4: If needed, keep track of some additional info so that the algorithm from Step 3 can find the actual solution.
- Step 5: If needed, code this up like a reasonable person.

(Pass)

#### What have we learned?

- We can solve unbounded knapsack in time O(nW).
  - If there are n items and our knapsack has capacity W.

- We again went through the steps to create DP solution:
  - We kept a one-dimensional table, creating smaller problems by making the knapsack smaller.



Capacity: 10











Weight:

Item:

6

2

4

3

11

Value:

20

8

14

13

35

#### Unbounded Knapsack:

- Suppose I have infinite copies of all of the items.
- What's the most valuable way to fill the knapsack?









Total weight: 10 Total value: 42



#### 0/1 Knapsack:

- Suppose I have only one copy of each item.
- What's the most valuable way to fill the knapsack?







Total weight: 9
Total value: 35

#### Recipe for applying Dynamic Programming

• Step 1: Identify optimal substructure.

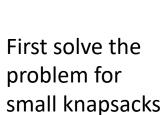


- Step 2: Find a recursive formulation for the value of the optimal solution.
- Step 3: Use dynamic programming to find the value of the optimal solution.
- Step 4: If needed, keep track of some additional info so that the algorithm from Step 3 can find the actual solution.
- Step 5: If needed, code this up like a reasonable person.

# Optimal substructure: try 1

- Sub-problems:
  - Unbounded Knapsack with a smaller knapsack.







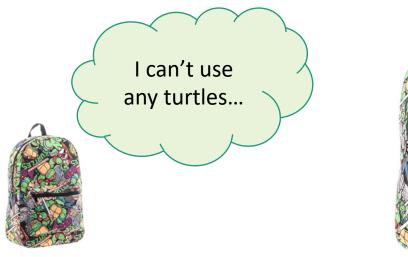
Then larger knapsacks



Then larger knapsacks

# This won't quite work...

- We are only allowed one copy of each item.
- The sub-problem needs to "know" what items we've used and what we haven't.





# Optimal substructure: try 2

• Sub-problems:

• 0/1 Knapsack with fewer items.

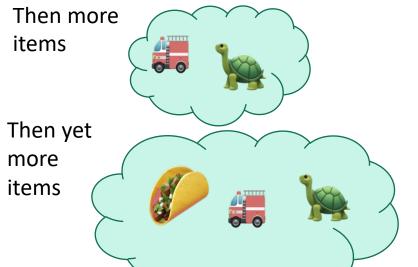




First solve the problem with few items



We'll still increase the size of the knapsacks.



(We'll keep a two-dimensional table).

# Our sub-problems:

Indexed by x and j



Capacity x

K[x,j] = optimal solution for a knapsack of size x using only the first j items.

#### Relationship between sub-problems

• Want to write K[x,j] in terms of smaller sub-problems.





Capacity x

K[x,j] = optimal solution for a knapsack of size x using only the first j items.



- Case 1: Optimal solution for j items does not use item j.
- Case 2: Optimal solution for j items does use item j.



Capacity x

K[x,j] = optimal solution for a knapsack of size x using only the first j items.



• Case 1: Optimal solution for j items does not use item j.



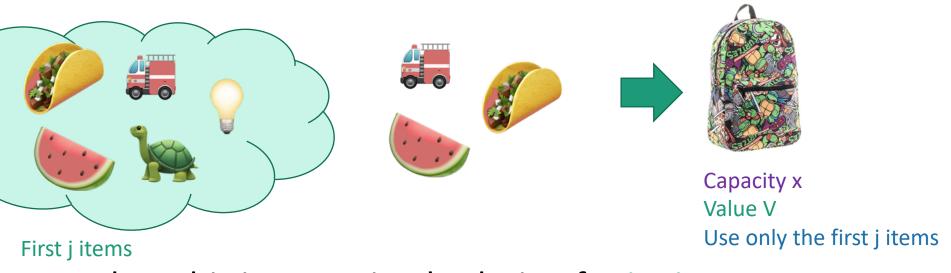
What lower-indexed problem should we solve to solve this problem?

1 min think; (wait) 1 min share





Case 1: Optimal solution for j items does not use item j.

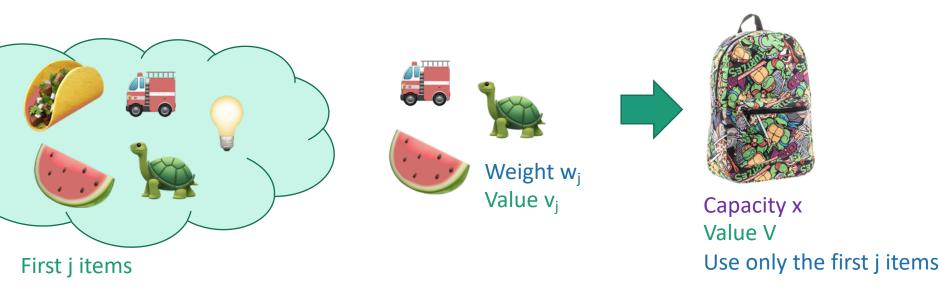


Then this is an optimal solution for j-1 items:





• Case 2: Optimal solution for j items uses item j.



What lower-indexed problem should we solve to solve this problem?

1 min think; (wait) 1 min share





Case 2: Optimal solution for j items uses item j.



• Then this is an optimal solution for j-1 items and a

smaller knapsack:







Capacity  $x - w_j$ Value  $V - v_j$ Use only the first j-12items.

### Recipe for applying Dynamic Programming

- Step 1: Identify optimal substructure.
- Step 2: Find a recursive formulation for the value of the optimal solution.
- Step 3: Use dynamic programming to find the value of the optimal solution.
- Step 4: If needed, keep track of some additional info so that the algorithm from Step 3 can find the actual solution.
- Step 5: If needed, code this up like a reasonable person.

# Recursive relationship

- Let K[x,j] be the optimal value for:
  - capacity x,
  - with j items.

$$K[x,j] = max\{ K[x, j-1], K[x - w_{j,} j-1] + v_{j} \}$$
Case 1

Case 2

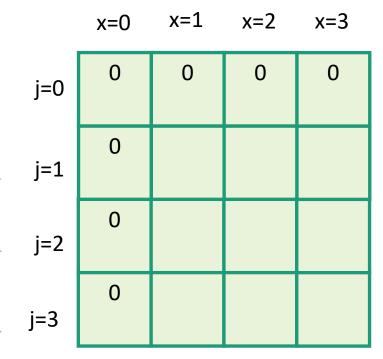
• (And K[x,0] = 0 and K[0,j] = 0).

### Recipe for applying Dynamic Programming

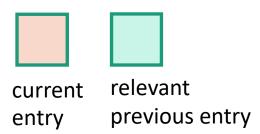
- Step 1: Identify optimal substructure.
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- Step 5: If needed, code this up like a reasonable person.

# Bottom-up DP algorithm

```
Zero-One-Knapsack(W, n, w, v):
   • K[x,0] = 0 for all x = 0,...,W
   • K[0,i] = 0 for all i = 0,...,n
   • for x = 1,...,W:
       • for j = 1,...,n:
                               Case 1
           • K[x,i] = K[x, i-1]
           • if w_i \leq x:
                                                Case 2
               • K[x,j] = max\{ K[x,j], K[x-w_i, j-1] + v_i \}
   return K[W,n]
```



- Zero-One-Knapsack(W, n, w, v):
  - K[x,0] = 0 for all x = 0,...,W
  - K[0,i] = 0 for all i = 0,...,n
  - for x = 1,...,W:
    - **for** j = 1,...,n:
      - K[x,j] = K[x, j-1]
      - if  $w_i \le x$ :
        - K[x,j] = max{ K[x,j], K[x - w<sub>j</sub>, j-1] + v<sub>j</sub> }
  - return K[W,n]





Weight: Value:









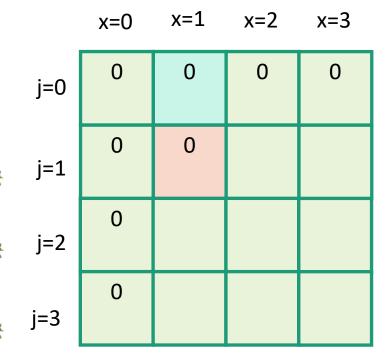


e: 1

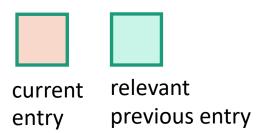
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6

Capacity: 3



- Zero-One-Knapsack(W, n, w, v):
  - K[x,0] = 0 for all x = 0,...,W
  - K[0,i] = 0 for all i = 0,...,n
  - for x = 1,...,W:
    - **for** j = 1,...,n:
      - K[x,j] = K[x, j-1]
      - if  $w_i \le x$ :
        - $K[x,j] = max\{K[x,j],$  $K[x - w_j, j-1] + v_j$
  - return K[W,n]













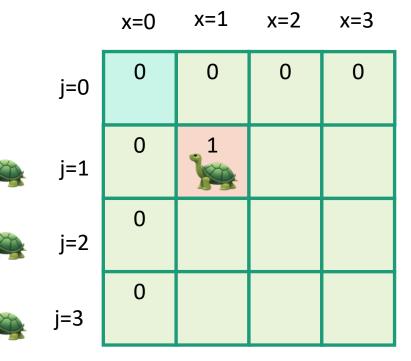




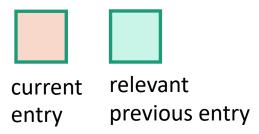
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3



- Zero-One-Knapsack(W, n, w, v):
  - K[x,0] = 0 for all x = 0,...,W
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  - for x = 1,...,W:
    - **for** j = 1,...,n:
      - K[x,j] = K[x, j-1]
      - if  $w_i \le x$ :
        - $K[x,j] = max\{ K[x,j],$  $K[x - w_j, j-1] + v_j$
  - return K[W,n]













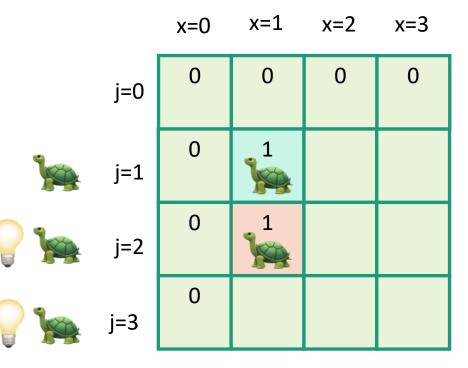
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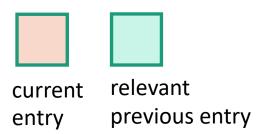
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- Zero-One-Knapsack(W, n, w, v):
  - K[x,0] = 0 for all x = 0,...,W
  - K[0,i] = 0 for all i = 0,...,n
  - for x = 1,...,W:
    - **for** j = 1,...,n:
      - K[x,j] = K[x, j-1]
      - if  $w_i \le x$ :
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  - return K[W,n]













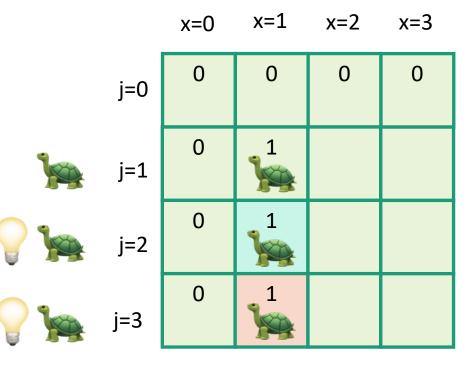
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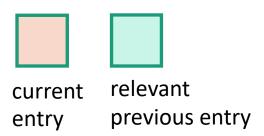








- Zero-One-Knapsack(W, n, w, v):
  - K[x,0] = 0 for all x = 0,...,W
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      - if  $w_i \le x$ :
        - $K[x,j] = max\{ K[x,j],$  $K[x - w_j, j-1] + v_j$
  - return K[W,n]













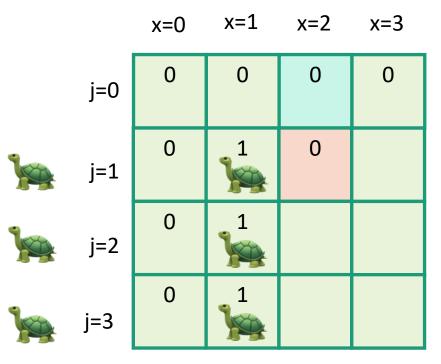
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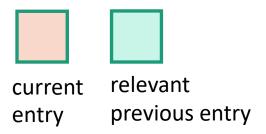


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      - if  $w_i \le x$ :
        - $K[x,j] = max\{ K[x,j],$  $K[x - w_j, j-1] + v_j$
  - return K[W,n]





Weight: Value:





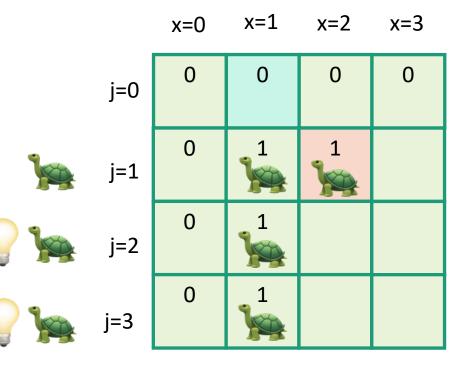




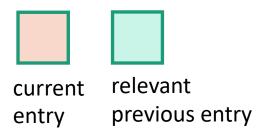


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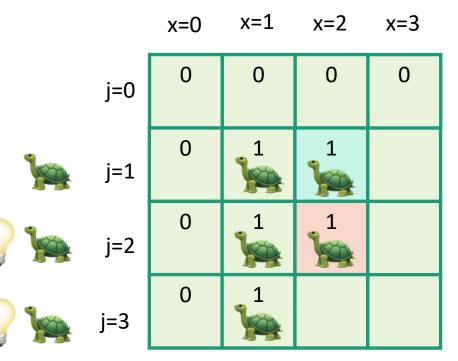
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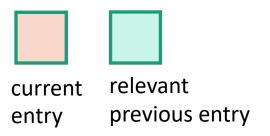


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  - for x = 1,...,W:
    - **for** j = 1,...,n:
      - K[x,j] = K[x, j-1]
      - if  $w_i \le x$ :
        - $K[x,j] = max\{ K[x,j],$  $K[x - w_j, j-1] + v_j$
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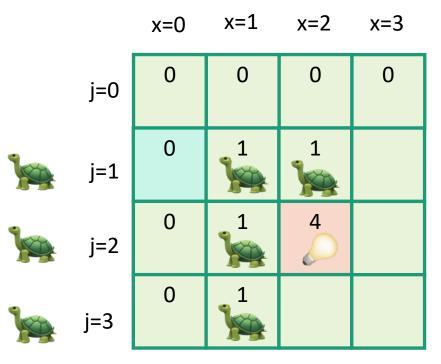
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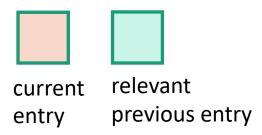
Capacity: 3

Value:

4



- Zero-One-Knapsack(W, n, w, v):
  - K[x,0] = 0 for all x = 0,...,W
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      - if  $w_i \le x$ :
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           K[x w<sub>j</sub>, j-1] + v<sub>j</sub> }
  - return K[W,n]



Item:

Weight: Value:



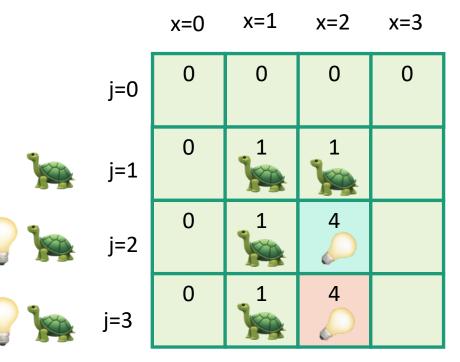




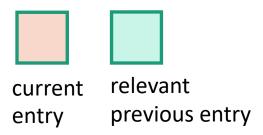




: 1 4 6 Capacity: 3



- Zero-One-Knapsack(W, n, w, v):
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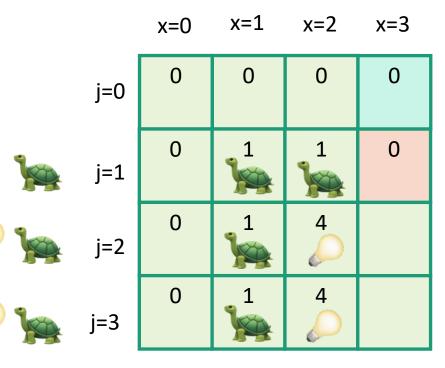




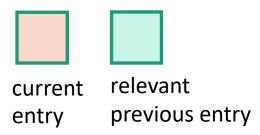
1 4

6

Capacity: 3



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      - K[x,j] = K[x, j-1]
      - if  $w_i \le x$ :
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  - return K[W,n]



Item:

Weight: Value:







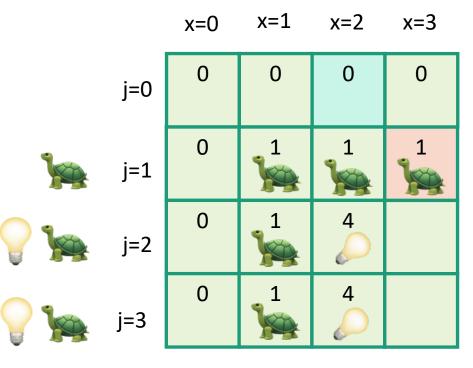




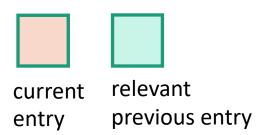
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3



- Zero-One-Knapsack(W, n, w, v):
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  - for x = 1,...,W:
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      - K[x,j] = K[x, j-1]
      - if  $w_i \le x$ :
        - $K[x,j] = max\{K[x,j],$  $K[x - w_j, j-1] + v_j$
  - return K[W,n]











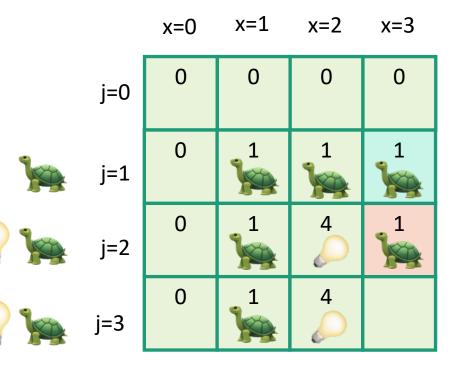




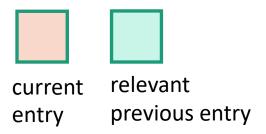


4

6



- Zero-One-Knapsack(W, n, w, v):
  - K[x,0] = 0 for all x = 0,...,W
  - K[0,i] = 0 for all i = 0,...,n
  - **for** x = 1,...,W:
    - **for** j = 1,...,n:
      - K[x,j] = K[x, j-1]
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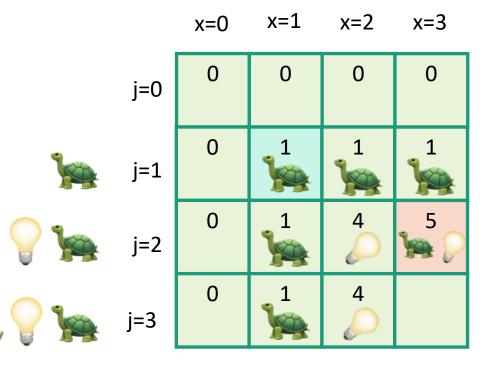




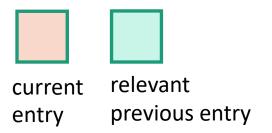


4

6



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        - K[x,j] = max{ K[x,j],
           K[x w<sub>j</sub>, j-1] + v<sub>j</sub> }
  - return K[W,n]



Item:

Weight: Value: 1

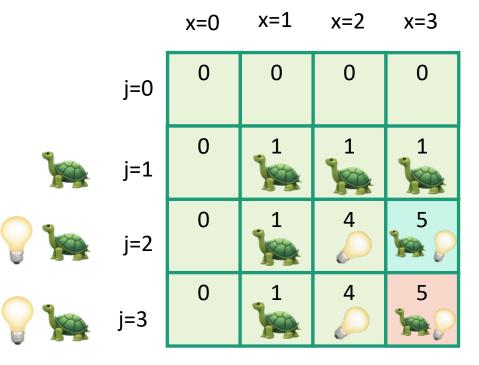
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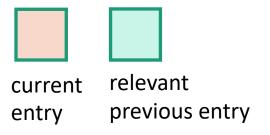
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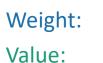




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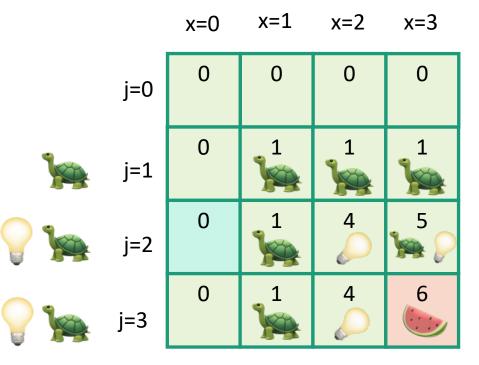
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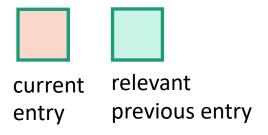








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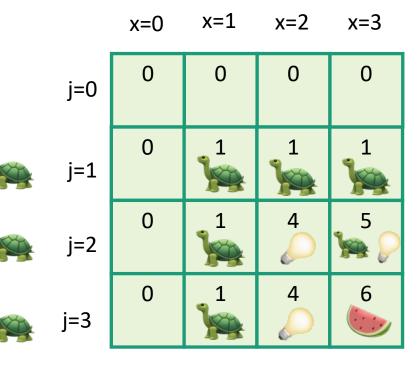


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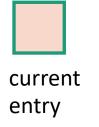






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      - if  $w_i \le x$ :
        - $K[x,j] = \max\{K[x,j], \\ K[x-w_i, j-1] + v_i\}$
  - return K[W,n]

So the optimal solution is to put one watermelon in your knapsack!





relevant previous entry



Weight: Value:









4





3



### Recipe for applying Dynamic Programming

- Step 1: Identify optimal substructure.
- Step 2: Find a recursive formulation for the value of the optimal solution.
- Step 3: Use dynamic programming to find the value of the optimal solution.
- Step 4: If needed, keep track of some additional info so that the algorithm from Step 3 can find the actual solution.
- **Step 5:** If needed, code this up like a reasonable person.

  You do this one!

(We did it on the slide in the previous example, just not in the pseudocode!)94

### What have we learned?

- We can solve 0/1 knapsack in time O(nW).
  - If there are n items and our knapsack has capacity W.

- We again went through the steps to create DP solution:
  - We kept a two-dimensional table, creating smaller problems by restricting the set of allowable items.

### Question

 How did we know which substructure to use in which variant of knapsack?

Answer in retrospect:





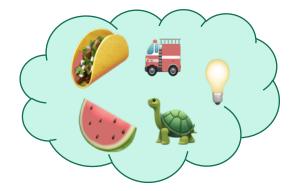


This one made sense for unbounded knapsack because it doesn't have any memory of what items have been used.

VS.



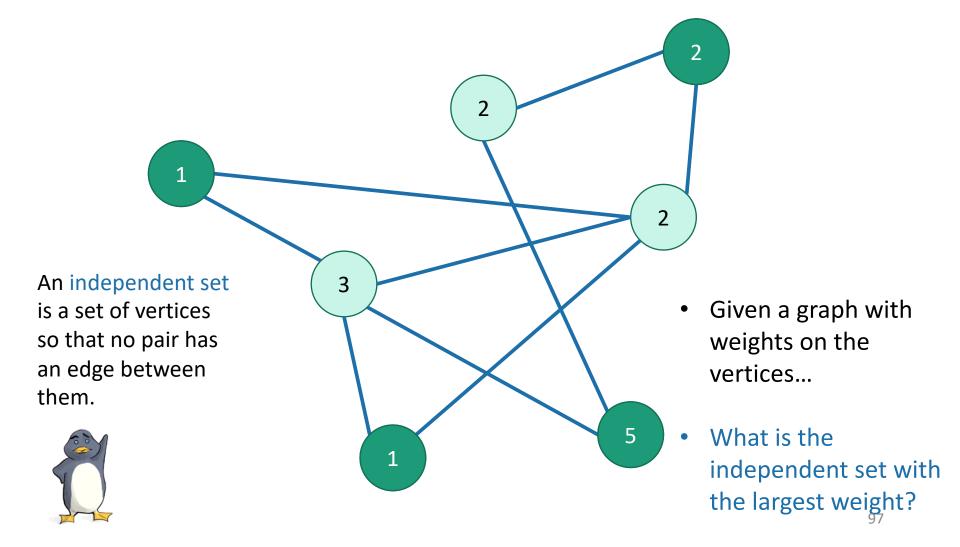




In 0/1 knapsack, we can only use each item once, so it makes sense to leave out one item at a time.

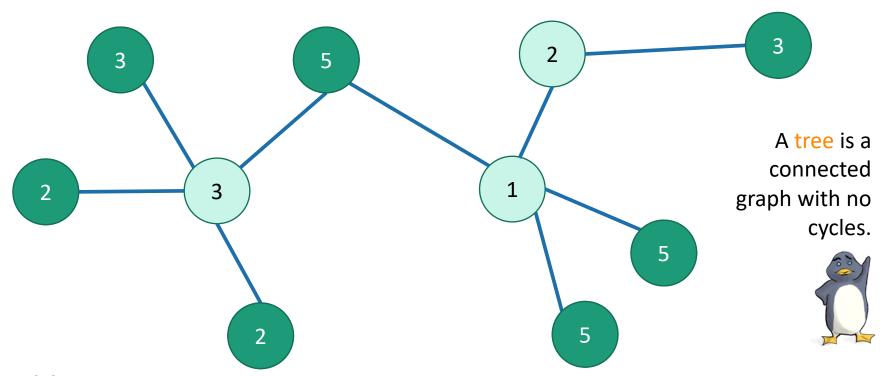
# Example 3: Independent Set

if we still have time



# Actually, this problem is NP-complete. So, we are unlikely to find an efficient algorithm.

• But if we also assume that the graph is a tree...



#### **Problem:**

find a maximal independent set in a tree (with vertex weights)?

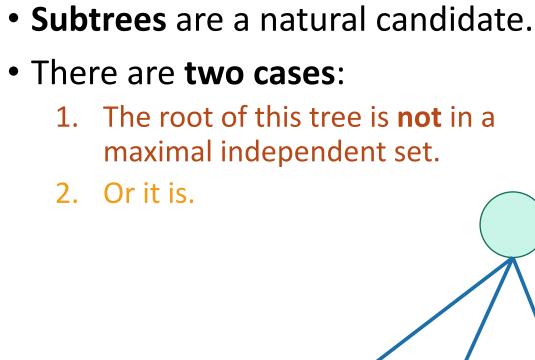
### Recipe for applying Dynamic Programming

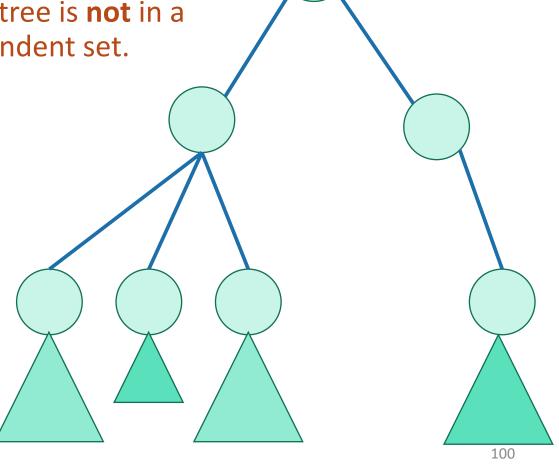
• Step 1: Identify optimal substructure.



- Step 2: Find a recursive formulation for the value of the optimal solution
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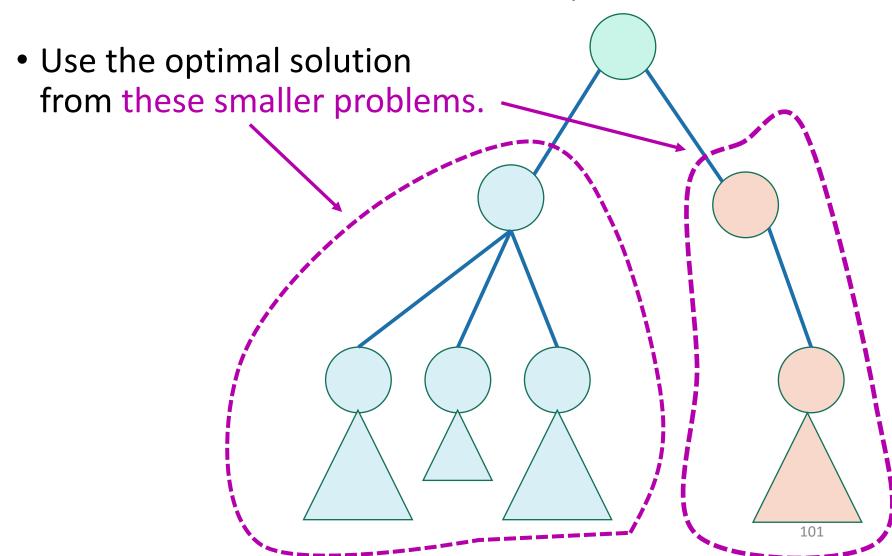
# Optimal substructure



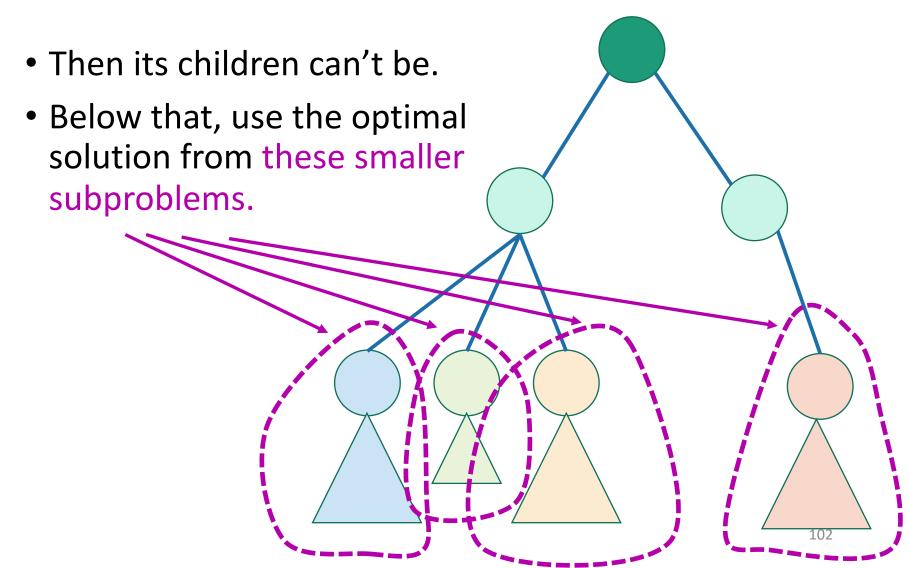


### Case 1:

the root is **not** in a maximal independent set



# Case 2: the root is in an maximal independent set



### Recipe for applying Dynamic Programming

- Step 1: Identify optimal substructure.
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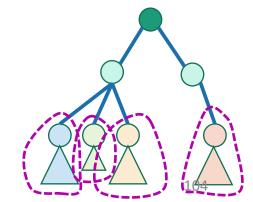
# Recursive formulation: try 1

• Let A[u] be the weight of a maximal independent set in the tree rooted at u.

• 
$$A[u] =$$

$$\max \begin{cases} \sum_{v \in u.\text{children } A[v]} \sum_{v \in u.\text{grandchildren } A[v]} \sum_{v \in u.\text{grandchild$$

When we implement this, how do we keep track of this term?



# Recursive formulation: try 2

Keep two arrays!

- Let A[u] be the weight of a maximal independent set in the tree rooted at u.
- Let  $B[u] = \sum_{v \in u. \text{children}} A[v]$

• 
$$A[u] = \max \begin{cases} \sum_{v \in u.\text{children}} A[v] \\ \text{weight}(u) + \sum_{v \in u.\text{children}} B[v] \end{cases}$$

### Recipe for applying Dynamic Programming

- Step 1: Identify optimal substructure.
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# A top-down DP algorithm

- MIS\_subtree(u):
  - if u is a leaf:
    - A[u] = weight(u)
    - B[u] = 0
  - else:
    - **for** v in u.children:
      - MIS\_subtree(v)
    - $A[u] = \max\{\sum_{v \in u, \text{children}} A[v], \text{ weight}(u) + \sum_{v \in u, \text{children}} B[v]\}$
    - $B[u] = \sum_{v \in u.\text{children}} A[v]$
- MIS(T):
  - MIS\_subtree(T.root)
  - return A[T.root]

Initialize global arrays A, B the recursive calls.

#### **Running time?**

- We visit each vertex once, and for every vertex we do O(1) work:
  - Make a recursive call
  - Participate in summations of parent node
- Running time is O(|V|)

### Why is this different from divide-and-conquer?

That's always worked for us with tree problems before...

- MIS subtree(u):
  - **if** u is a leaf:
    - return weight(u)
  - else:
- instead of looking up A[v] or B[v]. • return  $\max\{\sum_{v \in u.\text{children}} \text{MIS\_subtree}(v)$ ,

```
weight(u) + \sum_{v \in u.\text{grandchildren}} \text{MIS\_subtree}(v) }
```

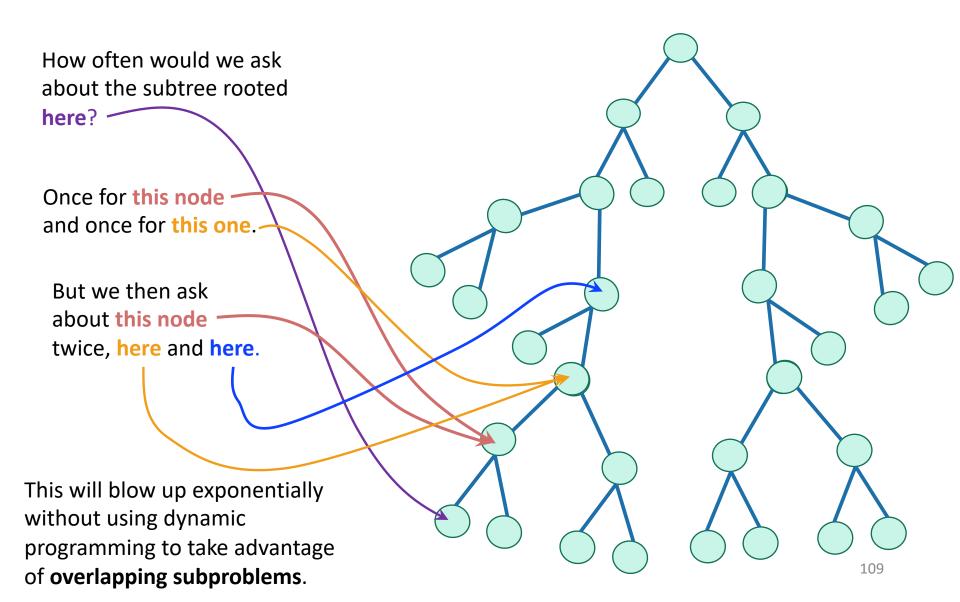
This is exactly the same pseudocode, except we've ditched the table and

are just calling MIS\_subtree(v)

- MIS(T):
  - return MIS subtree(T.root)

### Why is this different from divide-and-conquer?

That's always worked for us with tree problems before...



## Recipe for applying Dynamic Programming

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  You do this one!

### What have we learned?

 We can find maximal independent sets in trees in time O(|V|) using dynamic programming!

 For this example, it was natural to implement our DP algorithm in a top-down way.

## Recap

- Today we saw examples of how to come up with dynamic programming algorithms.
  - Longest Common Subsequence
  - Knapsack two ways
  - (If time) maximal independent set in trees.
- There is a **recipe** for dynamic programming algorithms.

### Recipe for applying Dynamic Programming

- Step 1: Identify optimal substructure.
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# Recap



- Today we saw examples of how to come up with dynamic programming algorithms.
  - Longest Common Subsequence
  - Knapsack two ways
  - (If time) maximal independent set in trees.
- There is a **recipe** for dynamic programming algorithms.
- Sometimes coming up with the right substructure takes some creativity
  - Practice on homework!
  - For even more practice check out additional examples/practice problems in CLRS or section!

### Next time

Greedy algorithms!



### Before next time

- Pre-lecture exercise: Greed is good!
- Good luck on exam 3.