Lecture 13

More dynamic programming!

Longest Common Subsequences, Knapsack, and (if time) independent sets in trees.

Last time



Not coding in an action movie.



Last time



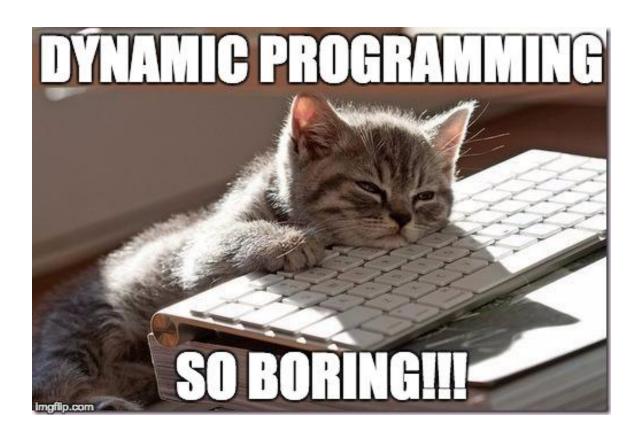
- Dynamic programming is an algorithm design paradigm.
- Basic idea:
 - Identify optimal sub-structure
 - Optimum to the big problem is built out of optima of small sub-problems
 - Take advantage of overlapping sub-problems
 - Only solve each sub-problem once, then use it again and again
 - Keep track of the solutions to sub-problems in a table as you build to the final solution.

Today

- Examples of dynamic programming:
 - 1. Longest common subsequence
 - 2. Knapsack problem
 - Two versions!
 - 3. Independent sets in trees
 - If we have time...
 - (If not the slides will be there as a reference)
- Yet more examples of DP in CLRS!
 - Optimal order of matrix multiplications
 - Optimal binary search trees
 - Longest paths in DAGs, ...

The goal of this lecture

For you to get really bored of dynamic programming



Longest Common Subsequence

How similar are these two species?



DNA:

AGCCCTAAGGGCTACCTAGCTT



DNA:
GACAGCCTACAAGCGTTAGCTTG

Longest Common Subsequence

How similar are these two species?



AGCCCTAAGGGCTACCTAGCTT



Pretty similar, their DNA has a long common subsequence:

AGCCTAAGCTTAGCTT

DNA:

Longest Common Subsequence

- Subsequence:
 - BDFH is a subsequence of ABCDEFGH
- If X and Y are sequences, a **common subsequence** is a sequence which is a subsequence of both.
 - BDFH is a common subsequence of ABCDEFGH and of ABDFGHI
- A longest common subsequence...
 - ...is a common subsequence that is longest.
 - The **longest common subsequence** of ABCDEFGH and ABDFGHI is ABDFGH.

We sometimes want to find these

Applications in bioinformatics





- The unix command diff
- Merging in version control
 - svn, git, etc...

```
🛅 anari — anari@nimbook —...
   ~ cat file1
   ~ cat file2
   ~ diff file1 file2
3d2
5d3
8a7
```

Recipe for applying Dynamic Programming

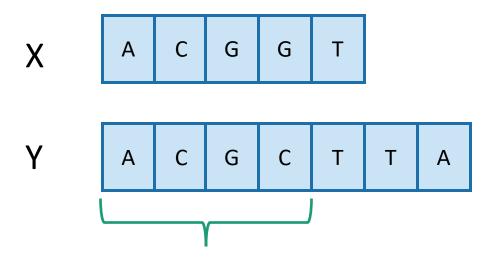
• Step 1: Identify optimal substructure.



- Step 2: Find a recursive formulation for the length of the longest common subsequence.
- Step 3: Use dynamic programming to find the length of the longest common subsequence.
- Step 4: If needed, keep track of some additional info so that the algorithm from Step 3 can find the actual LCS.
- Step 5: If needed, code this up like a reasonable person.

Step 1: Optimal substructure

Prefixes:



Notation: denote this prefix **ACGC** by Y₄

- Our sub-problems will be finding LCS's of prefixes to X and Y.
- Let C[i,j] = length_of_LCS(X_i, Y_i)

Recipe for applying Dynamic Programming

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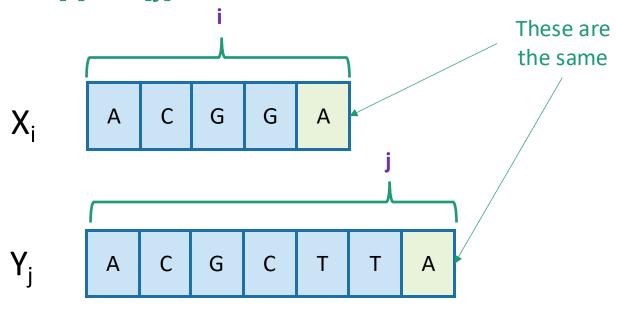
Goal

• Write C[i,j] in terms of the solutions to smaller subproblems

Two cases

Case 1: X[i] = Y[j]

- Our sub-problems will be finding LCS's of prefixes to X and Y.
- Let C[i,j] = length_of_LCS(X_i, Y_j)

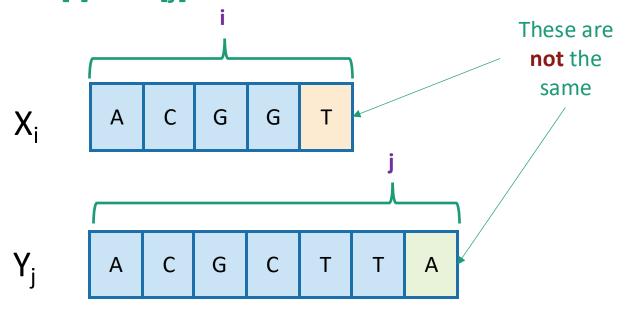


- Then C[i,j] = 1 + C[i-1,j-1].
 - because $LCS(X_i,Y_j) = LCS(X_{i-1},Y_{j-1})$ followed by

Two cases

Case 2: X[i] != Y[j]

- Our sub-problems will be finding LCS's of prefixes to X and Y.
- Let C[i,j] = length_of_LCS(X_i, Y_j)

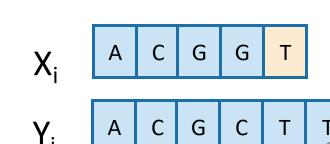


- Then C[i,j] = max{ C[i-1,j], C[i,j-1] }.
 - either $LCS(X_i, Y_j) = LCS(X_{i-1}, Y_j)$ and \top is not involved,
 - or LCS(X_i,Y_j) = LCS(X_i,Y_{j-1}) and A is not involved,
 - (maybe both are not involved, that's covered by the "or").

Recursive formulation of the optimal solution

•
$$C[i,j] = \begin{cases} 0 & \text{if } i = 0 \text{ or } j = 0 \\ C[i-1,j-1]+1 & \text{if } X[i] = Y[j] \text{ and } i,j > 0 \\ \max\{C[i,j-1],C[i-1,j]\} & \text{if } X[i] \neq Y[j] \text{ and } i,j > 0 \end{cases}$$

X_i A C G G A Y_j A C G C T T A



Case 2

Recipe for applying Dynamic Programming

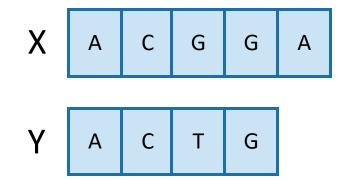
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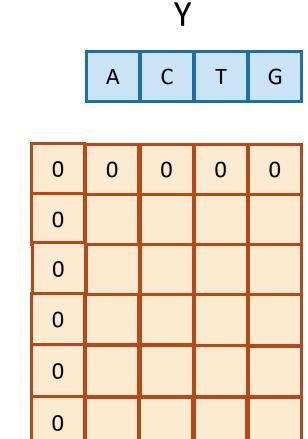
LCS DP

- LCS(X, Y):
 - C[i,0] = C[0,j] = 0 for all i = 0,...,m, j=0,...n.
 - **For** i = 1,...,m and j = 1,...,n:
 - **If** X[i] = Y[j]:
 - C[i,j] = C[i-1,j-1] + 1
 - Else:
 - C[i,j] = max{ C[i,j-1], C[i-1,j] }
 - Return C[m,n]

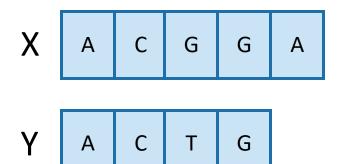
Running time: O(nm)

$$C[i,j] = \begin{cases} 0 & \text{if } i = 0 \text{ or } j = 0 \\ C[i-1,j-1] + 1 & \text{if } X[i] = Y[j] \text{ and } i,j > 0 \\ \max\{C[i,j-1],C[i-1,j]\} & \text{if } X[i] \neq Y[j] \text{ and } i \neq j > 0 \end{cases}$$





$$C[i,j] = \begin{cases} 0 & \text{if } i = 0 \text{ or } j = 0\\ C[i-1,j-1] + 1 & \text{if } X[i] = Y[j] \text{ and } i,j > 0\\ \max\{C[i,j-1],C[i-1,j]\} & \text{if } X[i] \neq Y[j] \text{ and } i,j > 0 \end{cases}$$



Υ					
А	С	Т	G		

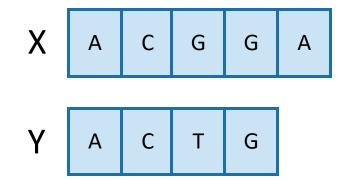
0	0	0	0	0
0	1	1	1	1
0	1	2	2	2
0	1	2	2	3
0	1	2	2	3
0	1	2	2	3

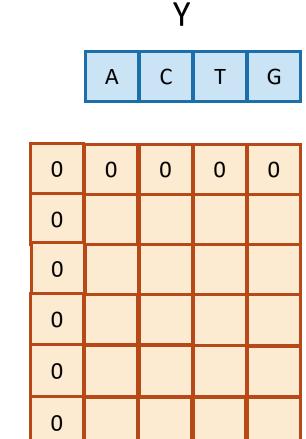
So the LCM of X and Y has length 3.

$$C[i,j] = \begin{cases} 0 & \text{if } i = 0 \text{ or } j = 0\\ C[i-1,j-1]+1 & \text{if } X[i] = Y[j] \text{ and } i,j > 0\\ \max\{C[i,j-1],C[i-1,j]\} & \text{if } X[i] \neq Y[j] \text{ and } i,j > 0 \end{cases}$$

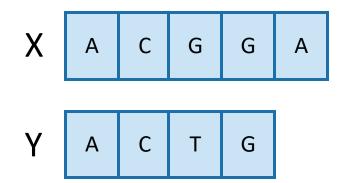
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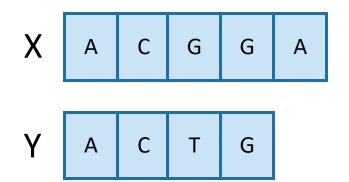
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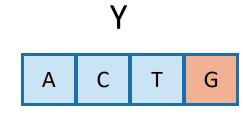


Υ					
А	С	Т	G		

0	0	0	0	0
0	1	1	1	1
0	1	2	2	2
0	1	2	2	3
0	1	2	2	3
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$$C[i,j] = \begin{cases} 0 & \text{if } i = 0 \text{ or } j = 0\\ C[i-1,j-1] + 1 & \text{if } X[i] = Y[j] \text{ and } i,j > 0\\ \max\{C[i,j-1],C[i-1,j]\} & \text{if } X[i] \neq Y[j] \text{ and } i,j > 0 \end{cases}$$

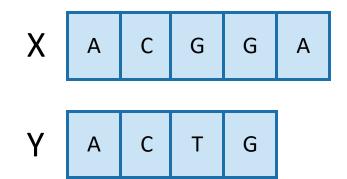


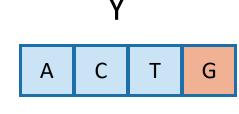


• Once we've filled this in, we can work backwards.

0	0	0	0	0
0	1	1	1	1
0	1	2	2	2
0	1	2	2	3
0	1	2	2	3
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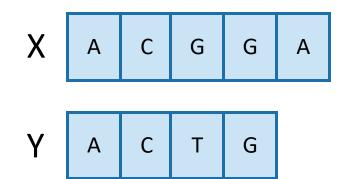


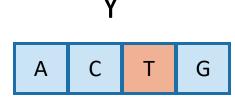
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0	0	0	0	0
0	1	1	1	1
0	1	2	2	2
0	1	2	2	3
0	1	2	2	3
0	1	2	2	3

That 3 must have come from the 3 above it.

$$C[i,j] = \begin{cases} 0 & \text{if } i = 0 \text{ or } j = 0\\ C[i-1,j-1] + 1 & \text{if } X[i] = Y[j] \text{ and } i,j > 0\\ \max\{C[i,j-1], C[i-1,j]\} & \text{if } X[i] \neq Y[j] \text{ and } i,j > 0 \end{cases}$$

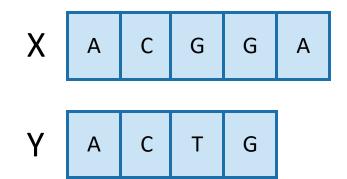


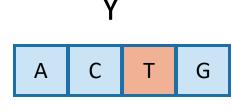


- Once we've filled this in, we can work backwards.
- A diagonal jump means that we found an element of the LCS!

This 3 came from that 2 – we found a match!

$$C[i,j] = \begin{cases} 0 & \text{if } i = 0 \text{ or } j = 0 \\ C[i-1,j-1]+1 & \text{if } X[i] = Y[j] \text{ and } i,j > 0 \\ \max\{C[i,j-1],C[i-1,j]\} & \text{if } X[i] \neq Y[j] \text{ and } i,j > 0 \end{cases}$$

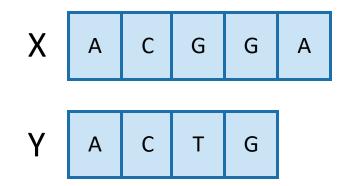


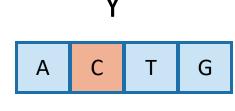


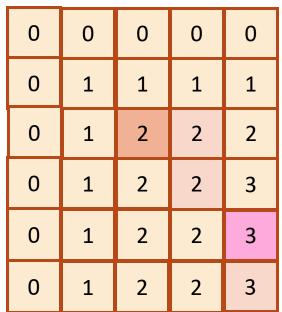
- Once we've filled this in, we can work backwards.
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That 2 may as well have come from this other 2.

$$C[i,j] = \begin{cases} 0 & \text{if } i = 0 \text{ or } j = 0 \\ C[i-1,j-1] + 1 & \text{if } X[i] = Y[j] \text{ and } i,j > 0 \\ \max\{C[i,j-1],C[i-1,j]\} & \text{if } X[i] \neq Y[j] \text{ and } i,j > 0 \end{cases}$$



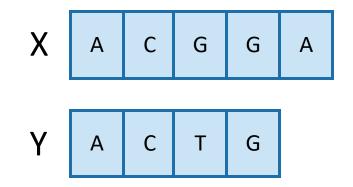


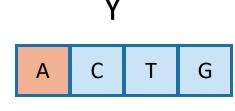


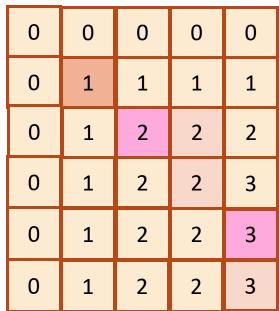
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G

$$C[i,j] = \begin{cases} 0 & \text{if } i = 0 \text{ or } j = 0\\ C[i-1,j-1] + 1 & \text{if } X[i] = Y[j] \text{ and } i,j > 0\\ \max\{C[i,j-1],C[i-1,j]\} & \text{if } X[i] \neq Y[j] \text{ and } i,j > 0 \end{cases}$$



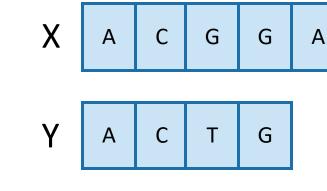


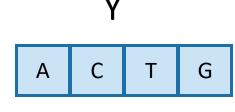


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CG

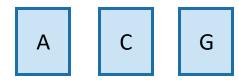
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0	0	0	0	0
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0	1	2	2	3

- Once we've filled this in, we can work backwards.
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This is the LCS!

$$C[i,j] = \begin{cases} 0 & \text{if } i = 0 \text{ or } j = 0\\ C[i-1,j-1] + 1 & \text{if } X[i] = Y[j] \text{ and } i,j > 0\\ \max\{C[i,j-1],C[i-1,j]\} & \text{if } X[i] \neq Y[j] \text{ and } i,j > 0 \end{cases}$$

Finding an LCS

- Good exercise to write out pseudocode for what we just saw!
 - Or you can find it in lecture notes.
- Takes time O(mn) to fill the table
- Takes time O(n + m) on top of that to recover the LCS
 - We walk up and left in an n-by-m array
 - We can only do that for n + m steps.
- Altogether, we can find LCS(X,Y) in time O(mn).

Recipe for applying Dynamic Programming

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Our approach actually isn't so bad

- If we are only interested in the length of the LCS we can do a bit better on space:
 - Since we go across the table one-row-at-a-time, we can only keep two rows if we want.
- If we want to recover the LCS, we need to keep the whole table.
- Can we do better than O(mn) time?
 - A bit better.
 - By a log factor or so.
 - But doing much better (polynomially better) is an open problem!

What have we learned?

- We can find LCS(X,Y) in time O(nm)
 - if |Y|=n, |X|=m
- We went through the steps of coming up with a dynamic programming algorithm.
 - We kept a 2-dimensional table, breaking down the problem by decrementing the length of X and Y.

Example 2: Knapsack Problem

We have n items with weights and values:

 Item:
 <th

- And we have a knapsack:
 - it can only carry so much weight:



Capacity: 10



Capacity: 10











Item: 11 Weight: 35 14 13 20 Value:

Unbounded Knapsack:

- Suppose I have infinite copies of all items.
- What's the most valuable way to fill the knapsack?









Total weight: 10 Total value: 42

• 0/1 Knapsack:

- Suppose I have only one copy of each item.
- What's the most valuable way to fill the knapsack?

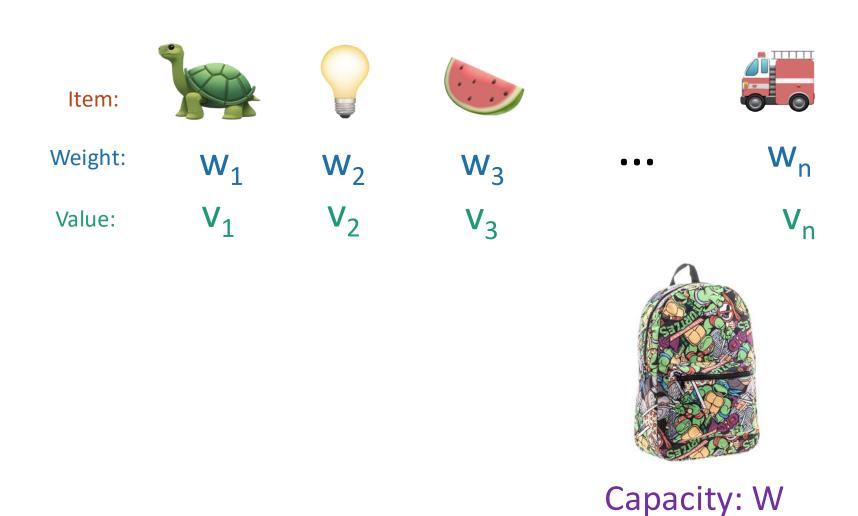






Total weight: 9 Total value: 35

Some notation



Recipe for applying Dynamic Programming

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- Step 2: Find a recursive formulation for the value of the optimal solution.
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Optimal substructure

• Sub-problems:

• Unbounded Knapsack with a smaller knapsack.

K[x] = value you can fit in a knapsack of capacity x







First solve the problem for small knapsacks

Then larger knapsacks

Then larger knapsacks

Optimal substructure



item i

Suppose this is an optimal solution for capacity x:

Say that the optimal solution contains at least one copy of item i.





Capacity x Value V

Then this is optimal for capacity x - w_i:











Why?
1 minute think
(wait) 1 minute share





Capacity $x - w_i$ Value V - v_i

Optimal substructure



👠 item i

Suppose this is an optimal solution for capacity x:

Say that the optimal solution contains at least one copy of item i.



• Then this is optimal for capacity x - w_i:





Capacity x

Value V

If I could do better than the second solution, then adding a turtle to that improvement would improve the first solution.

Capacity x – w_i Value V - v_i

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Recursive relationship

• Let K[x] be the optimal value for capacity x.

$$K[x] = \max_i \left\{ \begin{array}{c} + \\ \\ \end{array} \right\}$$
 The maximum is over all i so that $w_i \leq x$. Optimal way to fill the smaller knapsack

$$K[x] = max_i \{ K[x - w_i] + v_i \}$$

- (And K[x] = 0 if the maximum is empty).
 - That is, if there are no i so that $w_i \leq x$

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Let's write a bottom-up DP algorithm

- UnboundedKnapsack(W, n, weights, values):
 - K[0] = 0
 - for x = 1, ..., W:
 - K[x] = 0
 - **for** i = 1, ..., n:
 - if $w_i \leq x$:
 - $K[x] = \max\{K[x], K[x w_i] + v_i\}$
 - return K[W]

Running time: O(nW)

```
K[x] = \max_{i} \{ \left[ \left[ \left( x - w_{i} \right) + \left( v_{i} \right) \right] \right] 
= \max_{i} \{ \left[ \left( \left( x - w_{i} \right) + \left( v_{i} \right) \right] + \left( v_{i} \right) \right]
```

Can we do better?

- Writing down W takes log(W) bits.
- Writing down all n weights takes at most nlog(W) bits.
- Input size: nlog(W).
 - Maybe we could have an algorithm that runs in time O(nlog(W)) instead of O(nW)?
 - Or even O(n¹⁰⁰⁰⁰⁰⁰ log¹⁰⁰⁰⁰⁰⁰(W))?

- Open problem!
 - (But probably the answer is no...otherwise P = NP)

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 - for x = 1, ..., W:
 - K[x] = 0
 - **for** i = 1, ..., n:
 - if $w_i \leq x$:
 - $K[x] = \max\{K[x], K[x w_i] + v_i\}$
 - return K[W]

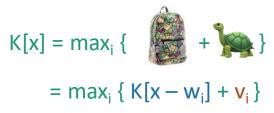
```
K[x] = \max_{i} \{ \left( \sum_{i=1}^{n} + \sum_{i=1}^{n} \right) \}
= \max_{i} \{ K[x - w_{i}] + v_{i} \}
```

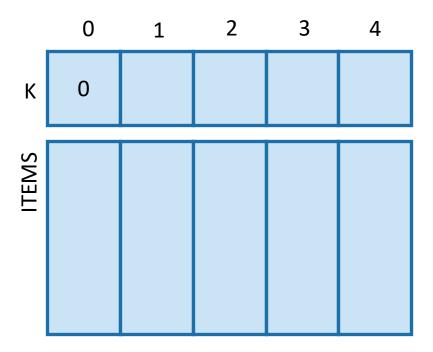
Let's write a bottom-up DP algorithm

UnboundedKnapsack(W, n, weights, values):

```
• K[0] = 0
• ITEMS[0] = Ø
• for x = 1, ..., W:
```

- K[x] = 0
- **for** i = 1, ..., n:
 - if $w_i \leq x$:
 - $K[x] = \max\{K[x], K[x w_i] + v_i\}$
 - If K[x] was updated:
 - ITEMS[x] = ITEMS[x − w_i] U { item i }
- return ITEMS[W]



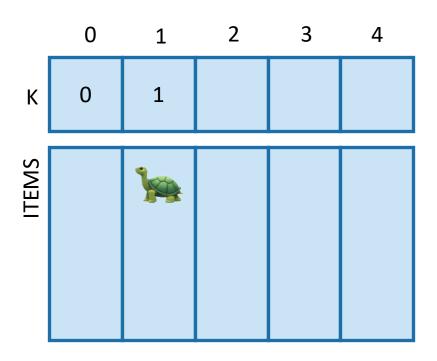


- UnboundedKnapsack(W, n, weights, values):
 - K[0] = 0
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 - for x = 1, ..., W:
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 - **for** i = 1, ..., n:
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Capacity: 4

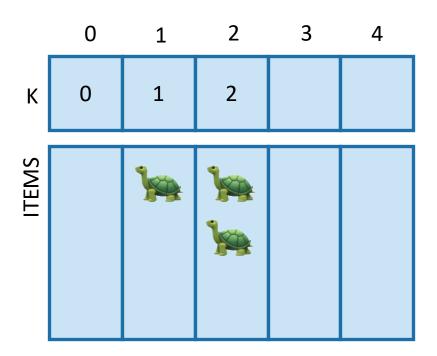


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Capacity: 4

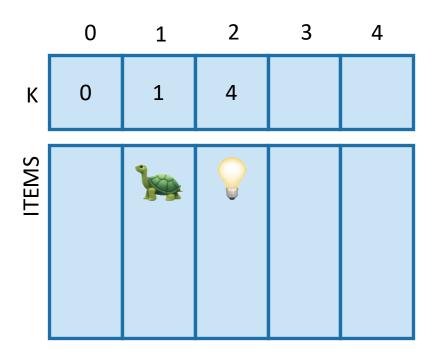


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 - ITEMS[x] = ITEMS[x w_i] \cup { item i }
 - return ITEMS[W]





Capacity: 4



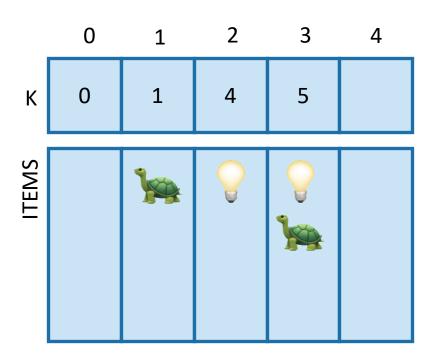
$$ITEMS[2] = ITEMS[0] +$$

- UnboundedKnapsack(W, n, weights, values):
 - K[0] = 0
 - ITEMS $[0] = \emptyset$
 - for x = 1, ..., W:
 - K[x] = 0
 - for i = 1, ..., n:
 - if $w_i \leq x$:
 - $K[x] = \max\{K[x], K[x w_i] + v_i\}$
 - If K[x] was updated:
 - ITEMS[x] = ITEMS[x w_i] U { item i }
 - return ITEMS[W]





Capacity: 4



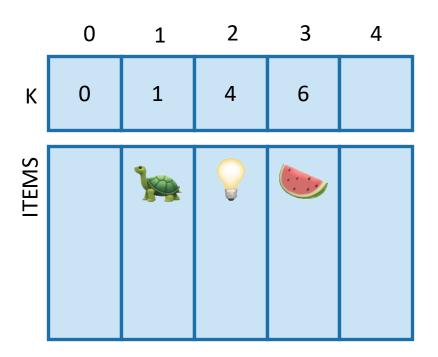
$$ITEMS[3] = ITEMS[2] +$$

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 - K[x] = 0
 - **for** i = 1, ..., n:
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 - If K[x] was updated:
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Capacity: 4

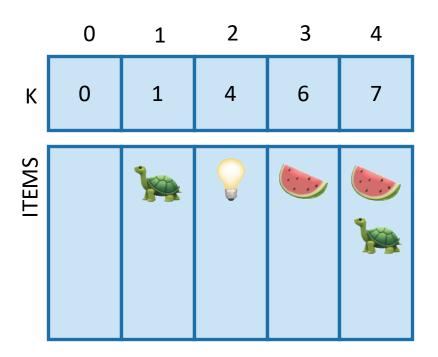


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Capacity: 4

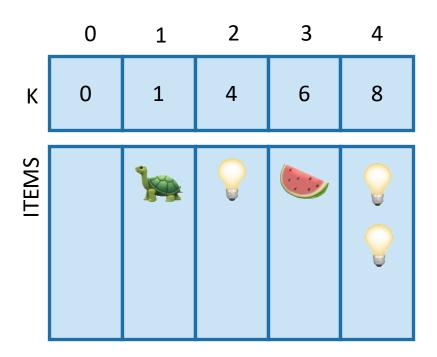


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 - If K[x] was updated:
 - ITEMS[x] = ITEMS[x w_i] \cup { item i }
 - return ITEMS[W]





Capacity: 4



$$ITEMS[4] = ITEMS[2] +$$

- UnboundedKnapsack(W, n, weights, values):
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 - for x = 1, ..., W:
 - K[x] = 0
 - for i = 1, ..., n:
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 - If K[x] was updated:
 - ITEMS[x] = ITEMS[x w_i] U { item i }
 - return ITEMS[W]





Capacity: 4

Recipe for applying Dynamic Programming

- Step 1: Identify optimal substructure.
- Step 2: Find a recursive formulation for the value of the optimal solution.
- Step 3: Use dynamic programming to find the value of the optimal solution.
- Step 4: If needed, keep track of some additional info so that the algorithm from Step 3 can find the actual solution.
- Step 5: If needed, code this up like a reasonable person.

(Pass)

What have we learned?

- We can solve unbounded knapsack in time O(nW).
 - If there are n items and our knapsack has capacity W.

- We again went through the steps to create DP solution:
 - We kept a one-dimensional table, creating smaller problems by making the knapsack smaller.



Capacity: 10



Weight:

Item:

11

Value:

20

14

13

35

Unbounded Knapsack:

- Suppose I have infinite copies of all of the items.
- What's the most valuable way to fill the knapsack?









Total weight: 10 Total value: 42



• 0/1 Knapsack:

- Suppose I have only one copy of each item.
- What's the most valuable way to fill the knapsack?







Total weight: 9 Total value: 35

Recipe for applying Dynamic Programming

Step 1: Identify optimal substructure.



- Step 2: Find a recursive formulation for the value of the optimal solution.
- Step 3: Use dynamic programming to find the value of the optimal solution.
- Step 4: If needed, keep track of some additional info so that the algorithm from Step 3 can find the actual solution.
- Step 5: If needed, code this up like a reasonable person.

Optimal substructure: try 1

- Sub-problems:
 - Unbounded Knapsack with a smaller knapsack.





First solve the problem for small knapsacks



Then larger knapsacks



Then larger knapsacks

This won't quite work...

- We are only allowed one copy of each item.
- The sub-problem needs to "know" what items we've used and what we haven't.



Optimal substructure: try 2

• Sub-problems:

• 0/1 Knapsack with fewer items.

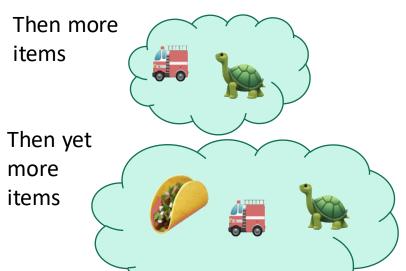




First solve the problem with few items



We'll still increase the size of the knapsacks.



(We'll keep a two-dimensional table).

Our sub-problems:

Indexed by x and j



Capacity x

K[x,j] = optimal solution for a knapsack of size x using only the first j items.

Relationship between sub-problems

• Want to write K[x,j] in terms of smaller sub-problems.





Capacity x

K[x,j] = optimal solution for a knapsack of size x using only the first j items.



- Case 1: Optimal solution for j items does not use item j.
- Case 2: Optimal solution for j items does use item j.



Capacity x

K[x,j] = optimal solution for a knapsack of size x using only the first j items.



• Case 1: Optimal solution for j items does not use item j.



What lower-indexed problem should we solve to solve this problem?

1 min think; (wait) 1 min share

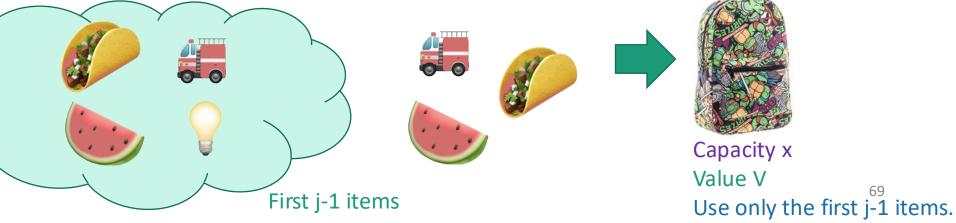




• Case 1: Optimal solution for j items does not use item j.

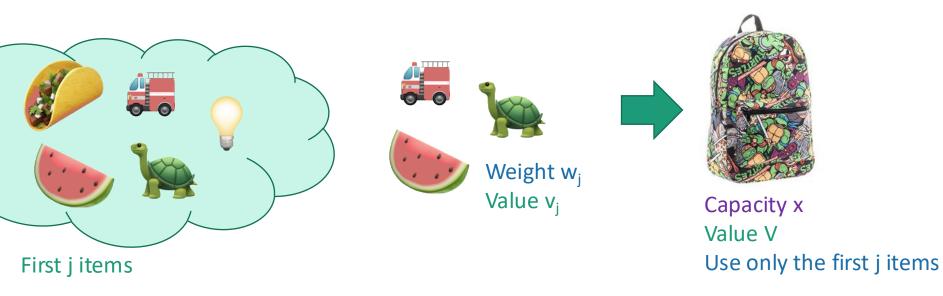


Then this is an optimal solution for j-1 items:





Case 2: Optimal solution for j items uses item j.



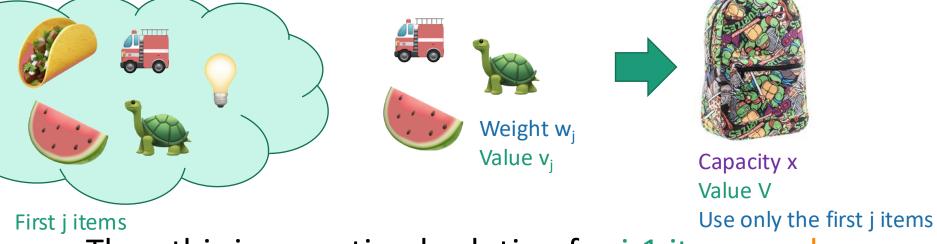
What lower-indexed problem should we solve to solve this problem?

1 min think; (wait) 1 min share





• Case 2: Optimal solution for j items uses item j.



Then this is an optimal solution for j-1 items and a



First j-1 items

Value $V - v_j$ Use only the first j-11items.

Recipe for applying Dynamic Programming

- Step 1: Identify optimal substructure.
- Step 2: Find a recursive formulation for the value of the optimal solution.
- Step 3: Use dynamic programming to find the value of the optimal solution.
- Step 4: If needed, keep track of some additional info so that the algorithm from Step 3 can find the actual solution.
- Step 5: If needed, code this up like a reasonable person.

Recursive relationship

- Let K[x,j] be the optimal value for:
 - capacity x,
 - with j items.

$$K[x,j] = max\{K[x, j-1], K[x - w_{j,} j-1] + v_{j}\}$$
Case 1
Case 2

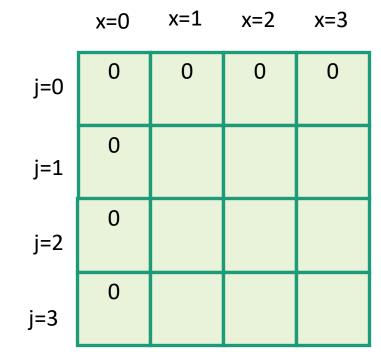
• (And K[x,0] = 0 and K[0,j] = 0).

Recipe for applying Dynamic Programming

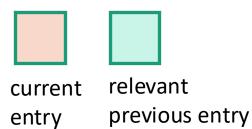
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Bottom-up DP algorithm

```
Zero-One-Knapsack(W, n, w, v):
   • K[x,0] = 0 for all x = 0,...,W
   • K[0,i] = 0 for all i = 0,...,n
   • for x = 1,...,W:
       • for j = 1,...,n:
                               Case 1
           • K[x,i] = K[x,i-1]
           • if w_i \leq x:
                                                Case 2
               • K[x,j] = max\{ K[x,j], K[x-w_i, j-1] + v_i \}
   return K[W,n]
```



- Zero-One-Knapsack(W, n, w, v):
 - K[x,0] = 0 for all x = 0,...,W
 - K[0,i] = 0 for all i = 0,...,n
 - for x = 1,...,W:
 - **for** j = 1,...,n:
 - K[x,j] = K[x, j-1]
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 K[x w_j, j-1] + v_j }
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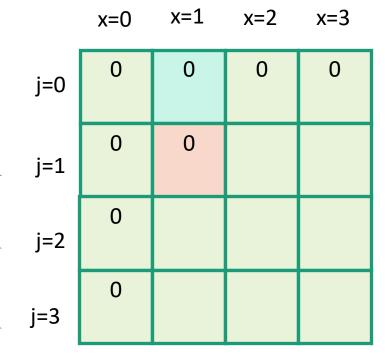


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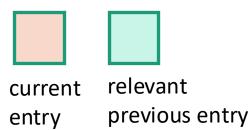








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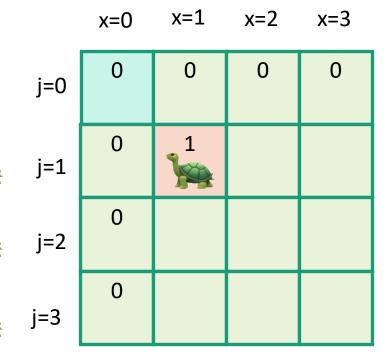




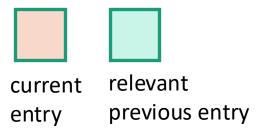




1 4 6



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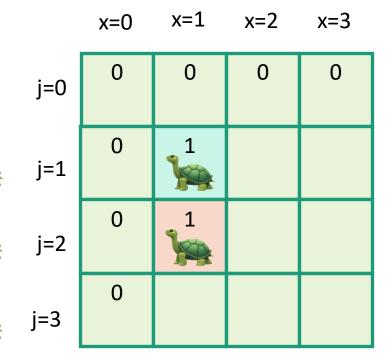
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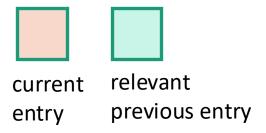


6





- Zero-One-Knapsack(W, n, w, v):
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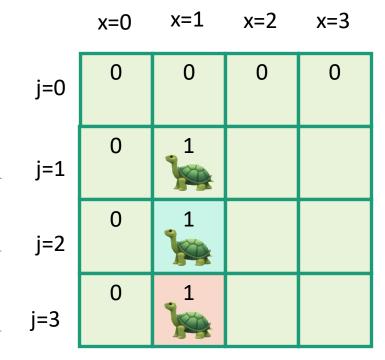




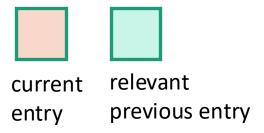


1 4

6



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6

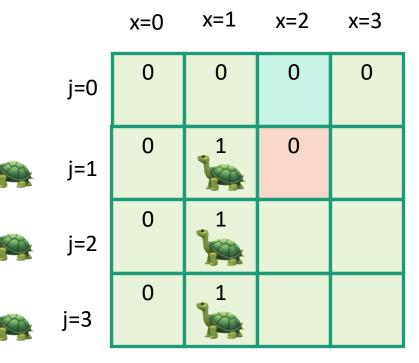


Capacity: 3

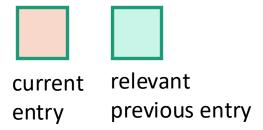
Value:

1

4



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4



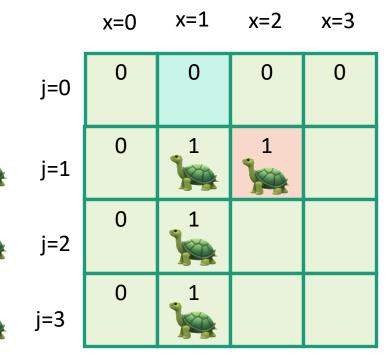




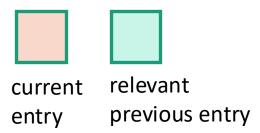
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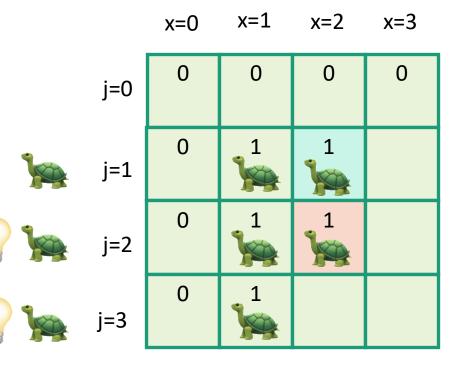
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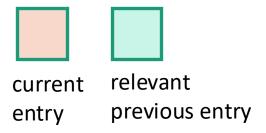




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4

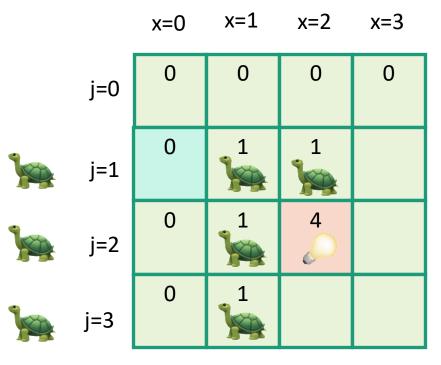




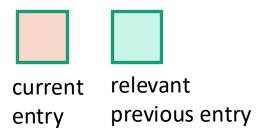




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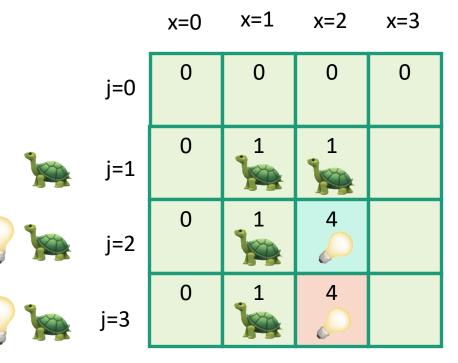


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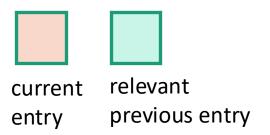


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Item:









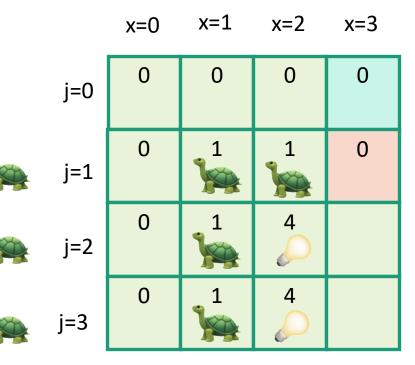
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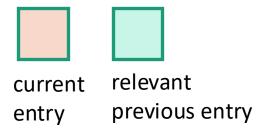


6





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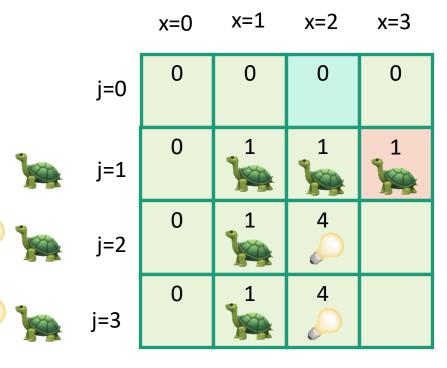




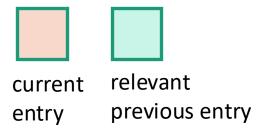
4

6

Capacity: 3



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 - if $w_i \le x$:
 - $K[x,j] = max\{K[x,j],$ $K[x - w_i, j-1] + v_i$
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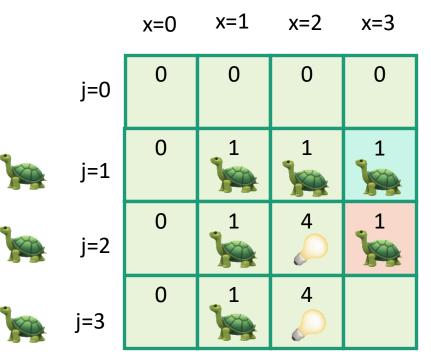




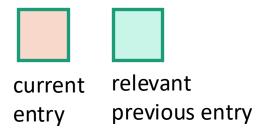




4



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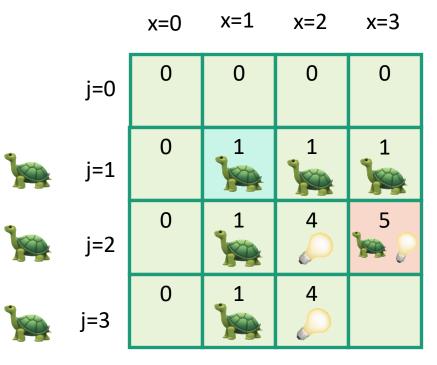




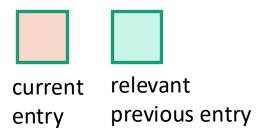


4

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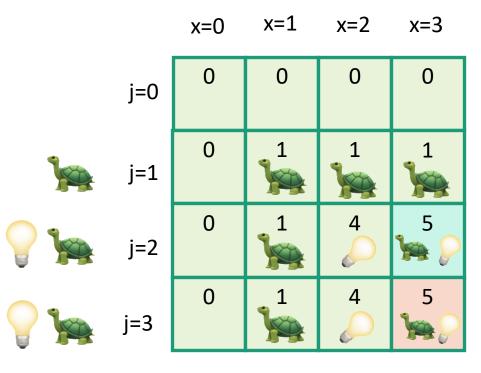
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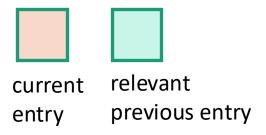


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 - K[x,j] = max{ K[x,j],
 K[x w_i, j-1] + v_i }
 - return K[W,n]













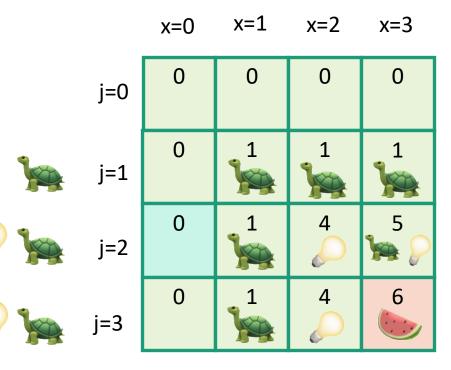




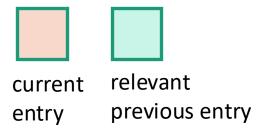
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3





- Zero-One-Knapsack(W, n, w, v):
 - K[x,0] = 0 for all x = 0,...,W
 - K[0,i] = 0 for all i = 0,...,n
 - for x = 1,...,W:
 - **for** j = 1,...,n:
 - K[x,j] = K[x, j-1]
 - if $w_i \le x$:
 - $K[x,j] = max\{K[x,j],$ $K[x - w_i, j-1] + v_i$
 - return K[W,n]













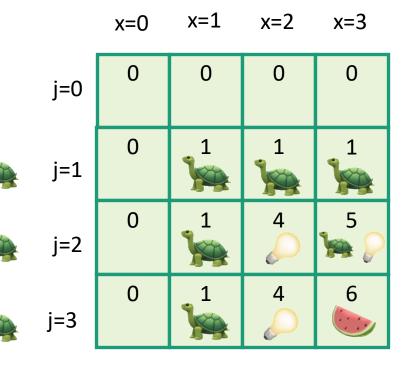
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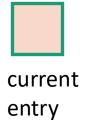
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- Zero-One-Knapsack(W, n, w, v):
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 - if $w_i \le x$:
 - $K[x,j] = max\{ K[x,j],$ $K[x - w_i, j-1] + v_i$
 - return K[W,n]

So the optimal solution is to put one watermelon in your knapsack!





relevant previous entry

















3





Capacity: 3

Recipe for applying Dynamic Programming

- Step 1: Identify optimal substructure.
- Step 2: Find a recursive formulation for the value of the optimal solution.
- Step 3: Use dynamic programming to find the value of the optimal solution.
- Step 4: If needed, keep track of some additional info so that the algorithm from Step 3 can find the actual solution.
- **Step 5:** If needed, code this up like a reasonable person.

 You do this one!

(We did it on the slide in the previous example, just not in the pseudocode!)93

What have we learned?

- We can solve 0/1 knapsack in time O(nW).
 - If there are n items and our knapsack has capacity W.

- We again went through the steps to create DP solution:
 - We kept a two-dimensional table, creating smaller problems by restricting the set of allowable items.

Question

 How did we know which substructure to use in which variant of knapsack?

Answer in retrospect:





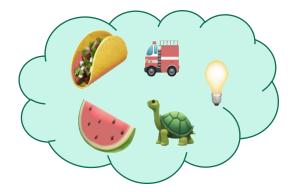


This one made sense for unbounded knapsack because it doesn't have any memory of what items have been used.

VS.



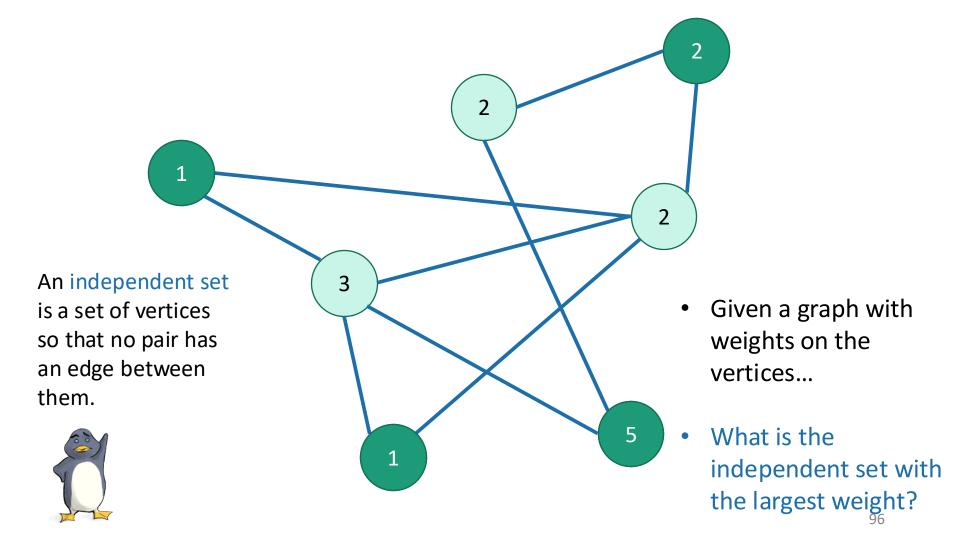




In 0/1 knapsack, we can only use each item once, so it makes sense to leave out one item at a time.

Example 3: Independent Set

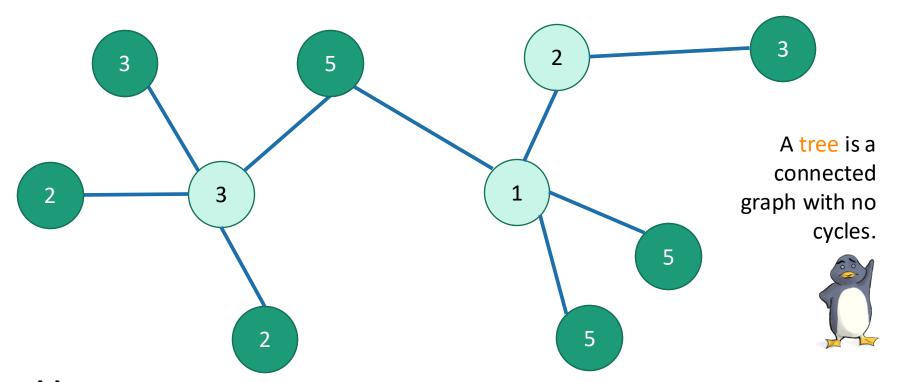
if we still have time



Actually, this problem is NP-complete.

So, we are unlikely to find an efficient algorithm.

• But if we also assume that the graph is a tree...



Problem:

find a maximal independent set in a tree (with vertex weights)?

Recipe for applying Dynamic Programming

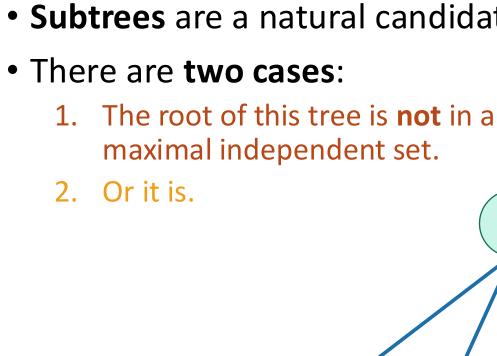
Step 1: Identify optimal substructure.

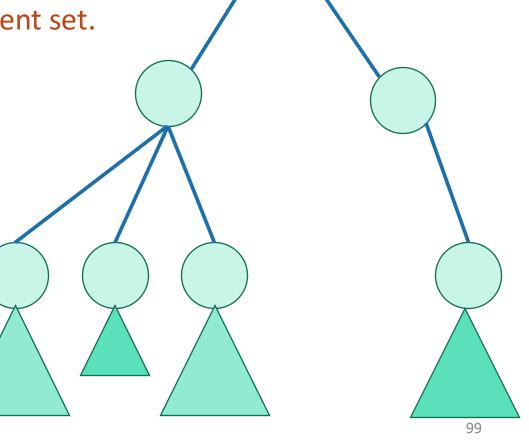


- Step 2: Find a recursive formulation for the value of the optimal solution
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Optimal substructure

• Subtrees are a natural candidate.

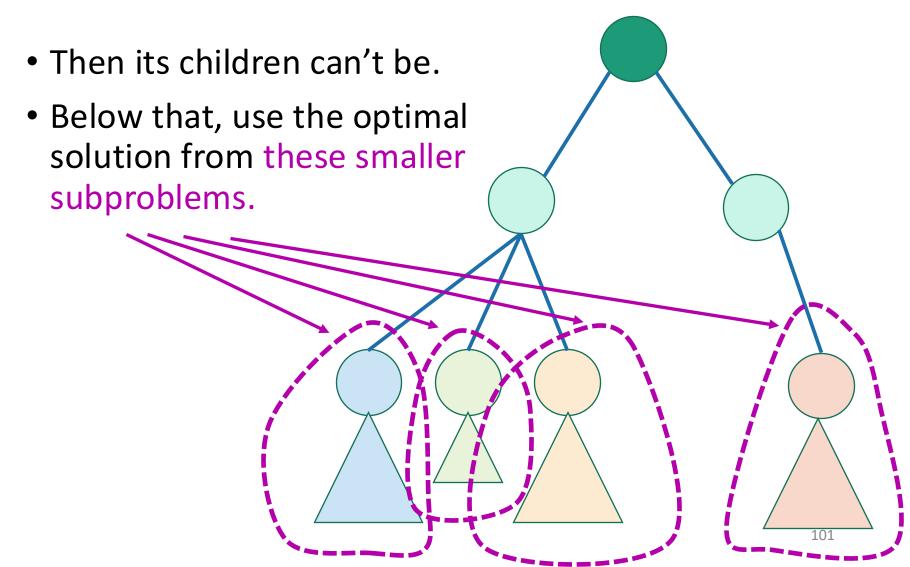




Case 1: the root is **not** in a maximal independent set

 Use the optimal solution from these smaller problems.

Case 2: the root is in an maximal independent set



Recipe for applying Dynamic Programming

- Step 1: Identify optimal substructure.
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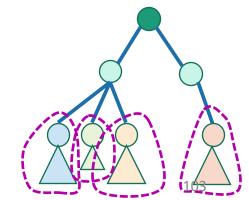
Recursive formulation: try 1

• Let A[u] be the weight of a maximal independent set in the tree rooted at u.

•
$$A[u] =$$

$$\max \begin{cases} \sum_{v \in u.\text{children } A[v]} \sum_{v \in u.\text{grandchildren } A[v]} \sum_{v \in u.\text{grandchild$$

When we implement this, how do we keep track of this term?



Recursive formulation: try 2

Keep two arrays!

- Let A[u] be the weight of a maximal independent set in the tree rooted at u.
- Let $B[u] = \sum_{v \in u. \text{children}} A[v]$

•
$$A[u] = \max \begin{cases} \sum_{v \in u.\text{children}} A[v] \\ \text{weight}(u) + \sum_{v \in u.\text{children}} B[v] \end{cases}$$

Recipe for applying Dynamic Programming

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A top-down DP algorithm

- MIS_subtree(u):
 - if u is a leaf:
 - A[u] = weight(u)
 - B[u] = 0
 - else:
 - **for** v in u.children:
 - MIS_subtree(v)
 - $A[u] = \max\{\sum_{v \in u. \text{children}} A[v], \text{ weight}(u) + \sum_{v \in u. \text{children}} B[v]\}$
 - $B[u] = \sum_{v \in u. \text{children}} A[v]$
- MIS(T):
 - MIS_subtree(T.root)
 - return A[T.root]

Initialize global arrays A, B the recursive calls.

Running time?

- We visit each vertex once, and for every vertex we do O(1) work:
 - Make a recursive call
 - Participate in summations of parent node

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• Running time is O(|V|)

Why is this different from divide-and-conquer?

That's always worked for us with tree problems before...

- MIS subtree(u):
 - if u is a leaf:
 - return weight(u)
 - else:
- instead of looking up A[v] or B[v]. • return $\max\{\sum_{v \in u. \text{children}} \text{MIS_subtree}(v)$,

```
weight(u) + \sum_{v \in u.grandchildren} MIS_subtree(<math>v) }
```

This is exactly the same pseudocode,

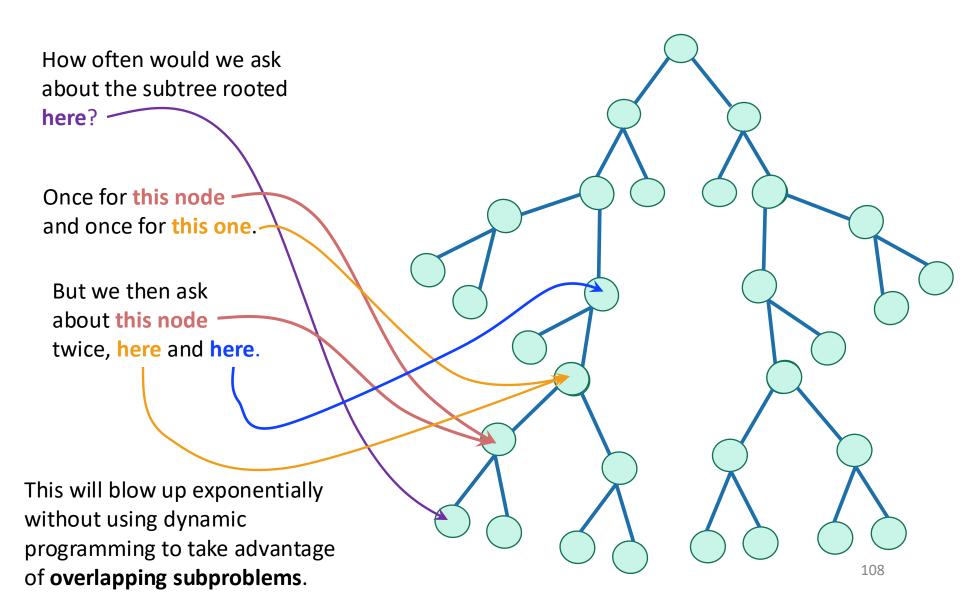
except we've ditched the table and

are just calling MIS_subtree(v)

- MIS(T):
 - return MIS subtree(T.root)

Why is this different from divide-and-conquer?

That's always worked for us with tree problems before...



Recipe for applying Dynamic Programming

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 You do this one!

What have we learned?

 We can find maximal independent sets in trees in time O(|V|) using dynamic programming!

 For this example, it was natural to implement our DP algorithm in a top-down way.

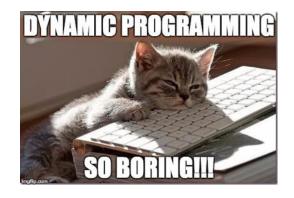
Recap

- Today we saw examples of how to come up with dynamic programming algorithms.
 - Longest Common Subsequence
 - Knapsack two ways
 - (If time) maximal independent set in trees.
- There is a **recipe** for dynamic programming algorithms.

Recipe for applying Dynamic Programming

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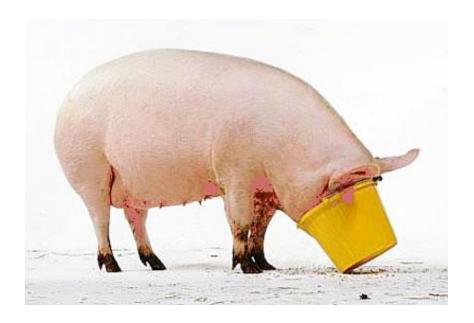
Recap



- Today we saw examples of how to come up with dynamic programming algorithms.
 - Longest Common Subsequence
 - Knapsack two ways
 - (If time) maximal independent set in trees.
- There is a **recipe** for dynamic programming algorithms.
- Sometimes coming up with the right substructure takes some creativity
 - Practice on homework!
 - For even more practice check out additional examples/practice problems in CLRS or section!

Next time

Greedy algorithms!



Before next time

• Pre-lecture exercise: Greed is good!